

DECIE

# PROIECT

***Concursul de Robotică RoboSmart  
al Universității din Pitești***

PENTRU ELEVII CLASELOR IX – XII

DEPARTAMENTUL DE  
ELECTRONICĂ, CALCULATOARE  
ȘI INGINERIE ELECTRICĂ

Sponsori

**TEXTRON**  
FLEET MANAGEMENT

Facultatea de Electronică, Comunicații și Calculatoare

Concurs de robotică

RoboSmart

## Cursul 3

Arduino. Structure. Components. Arduino IDE

Prezinta:

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*Cosmin Stirbu*

*Ionescu Valeriu*

Sponsori:

**TEXTRON**  
FLEET MANAGEMENT

# Outline

- Arduino versions
- Communication Protocols: I<sup>2</sup>C, SPI
- Interacting with the environment
- Arduino Uno
- IDE programming tools
- Examples

# Arduino boards

In 2013: 700,000  
official boards!



Arduino Micro



Arduino Uno



Arduino Due

Do It Yourself (DIY) projects!

ARM (**A**dvanced **RISC M**achine) architecture....

License:

GNU Lesser General Public License (LGPL) or  
GNU General Public License (GPL)

<https://www.arduino.cc>

<https://ardushop.ro>

# Arduino boards – types

ENTRY LEVEL	UNOLEONARDOT01ESPLORAMICRONANOMINIMKR2UNO ADAPTER STARTER KITLCD SCREEN
ENHANCED FEATURES	MEGAZERODUEMEGA ADKMO MO PROMKR ZEROMOTOR SHIELD USB HOST SHIELDPROTO SHIELDMKR PROTO SHIELD4 RELAYS SHIELD MEGA PROTO SHIELDMKR RELAY PROTO SHIELDISPUSB2SERIAL MICRO USB2SERIAL CONVERTER
INTERNET OF THINGS	YÚNETHERNETTIANINDUSTRIAL T01LEONARDO ETHMKR FOX 1200 MKR WAN 1300MKR GSM 1400MKR1000YUN MINICYÚN SHIELDWIRELESS SD SHIELD WIRELESS PROTO SHIELDETHERNET SHIELD V2GSM SHIELD V2MKR IoT BUNDLE
EDUCATION	CTC T01
WEARABLE	GEMMALILYPAD ARDUINO USBLILYPAD ARDUINO MAIN BOARDLILYPAD ARDUINO SIMPLE LILYPAD ARDUINO SIMPLE SNAP
3D PRINTING	MATERIA T01

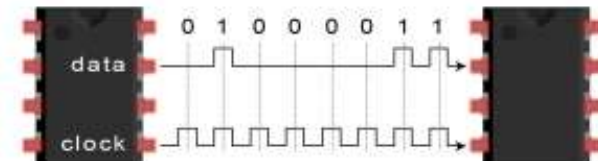
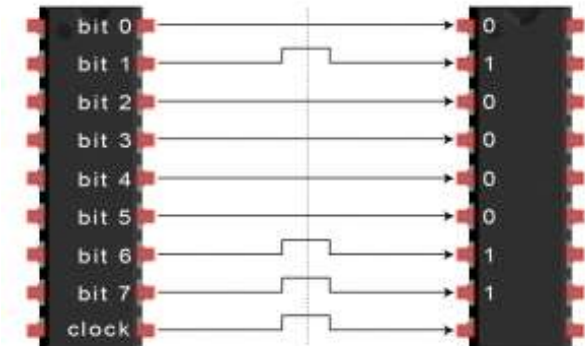
# Entry level





# Communication protocols

- Do you ever think about how the two devices talk to each other?
- Communication between electronic devices is like communication between humans. Both sides need to speak the same language. In electronics, these languages are called *communication protocols*.
- In DIY projects:
  - Parallel communication
    - High speed timing problems
  - Serial communication
    - Inter-Integrated Circuit (I2C)
    - Serial Peripheral Interface (SPI)



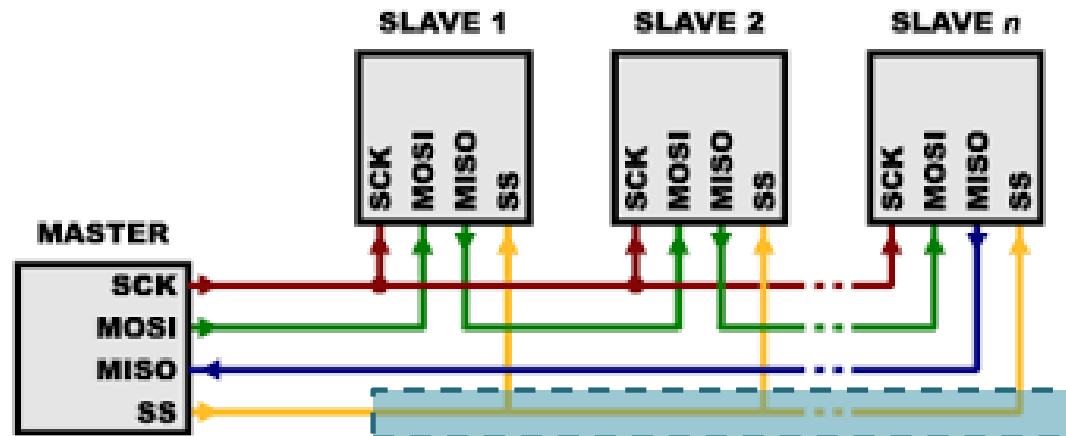
# Serial Peripheral Interface

Used in: SD cards, LCD and RFID readers

The SPI bus specifies four logic signals:

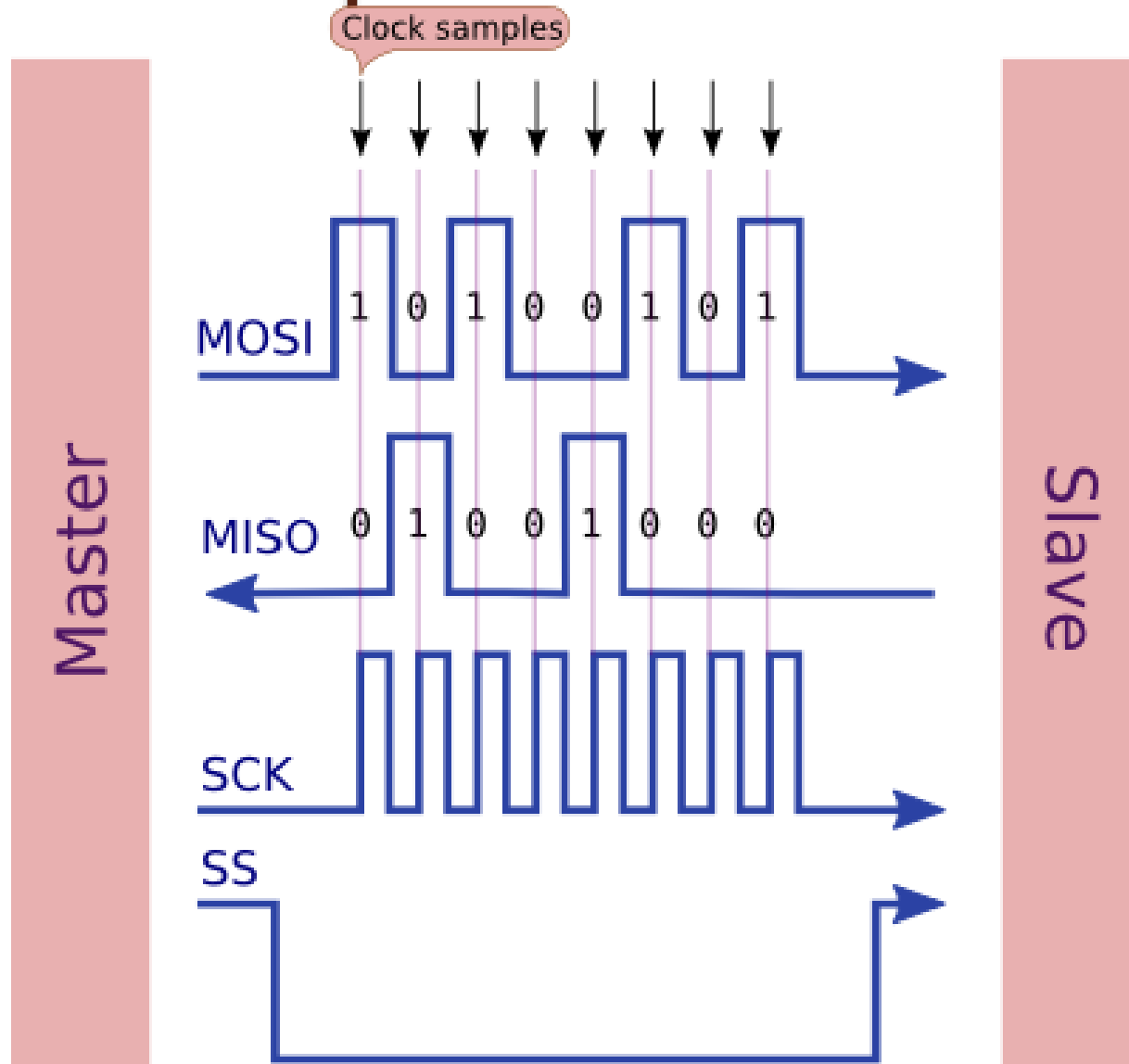
- **MISO/SDI** (Master In Slave Out) - The Slave line for sending data to the master,
- **MOSI/SDO** (Master Out Slave In) - The Master line for sending data to the peripherals,
- **SCK** (Serial Clock) - The clock pulses which synchronize data transmission generated by the master
- **SS**: Slave Select - An independent SS signal from master for each slave device!

Single master - multiple slaves!





# Serial Peripheral Interface

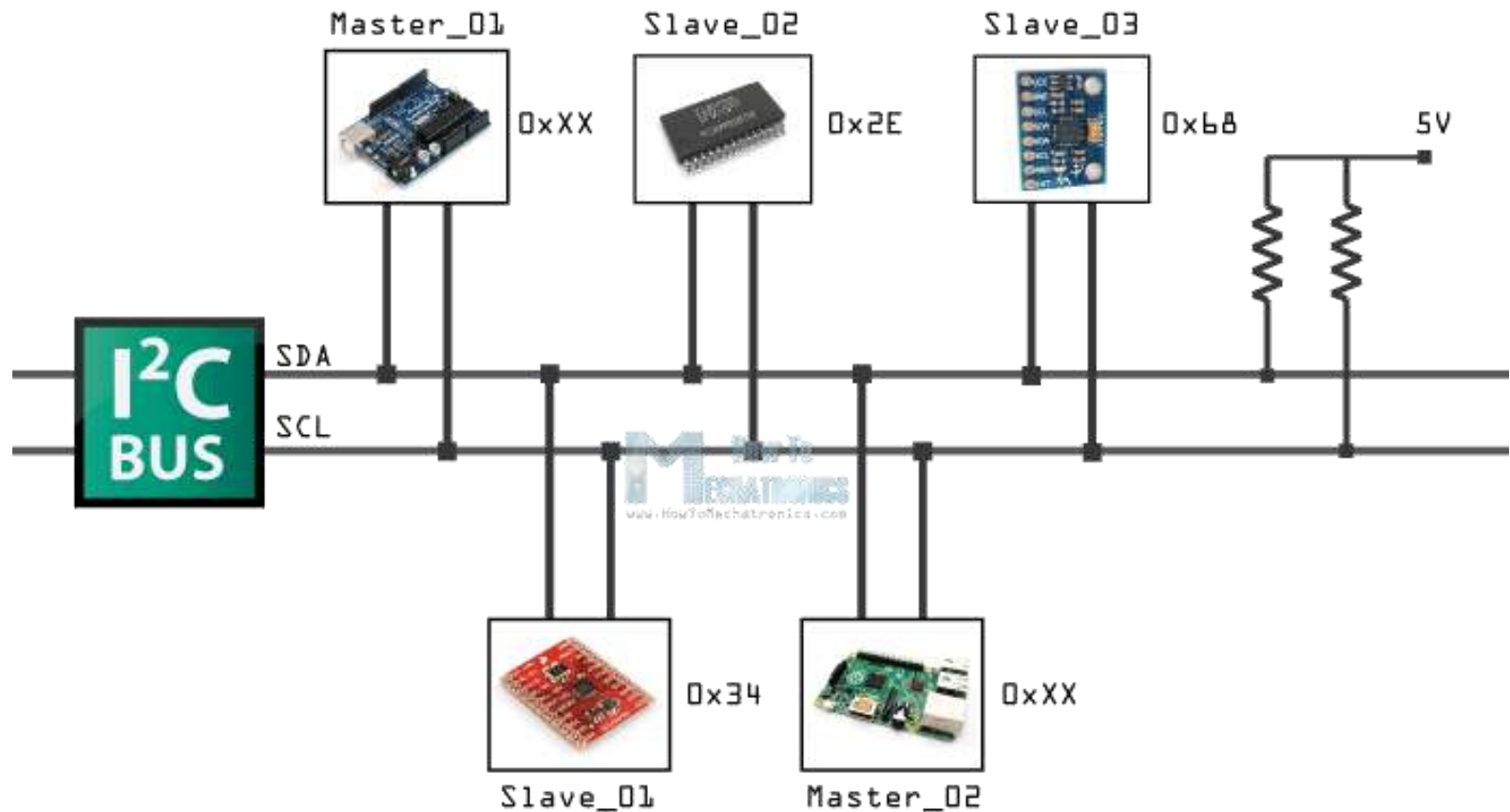


# Enhanced features



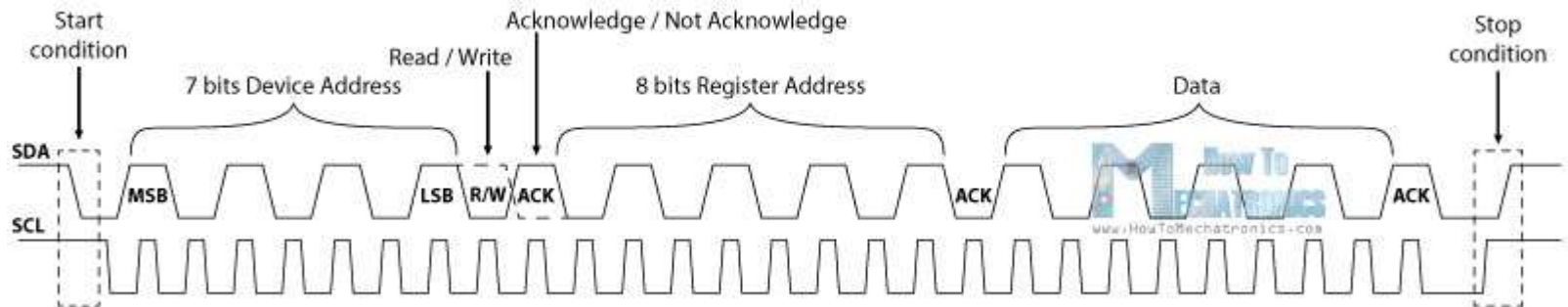
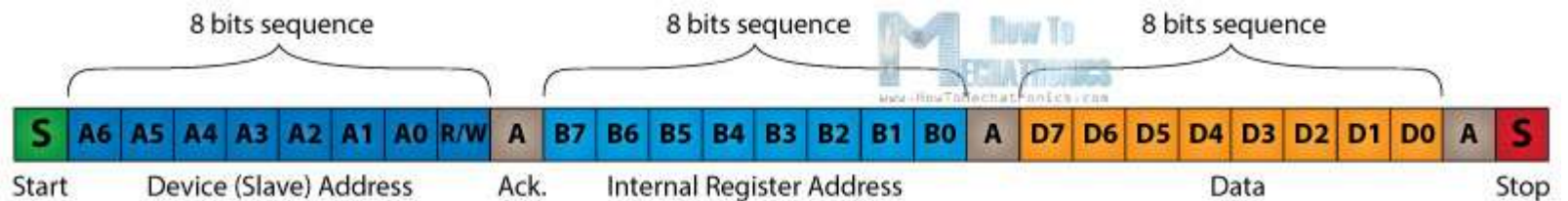
# Arduino boards

## ARDUINO MICRO



# Arduino boards

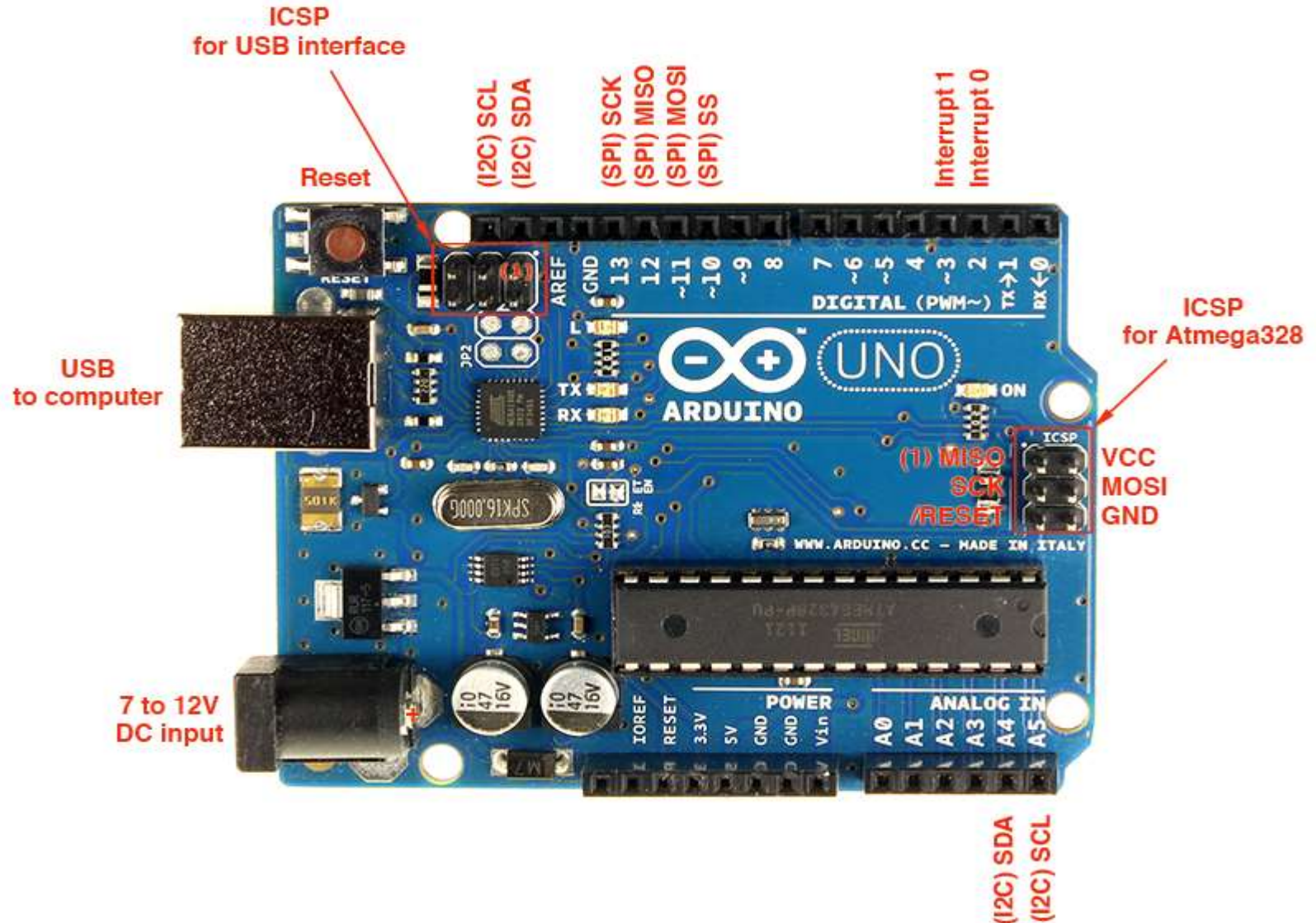
## ARDUINO MICRO



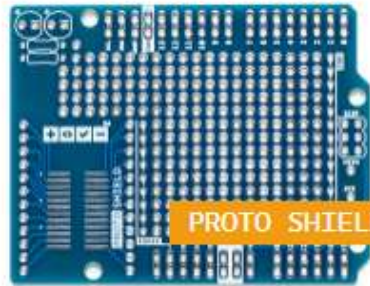
<https://www.arduino.cc/en/Reference/Wire>



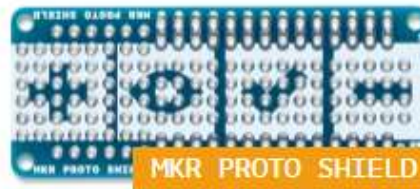
# Serial Peripheral Interface



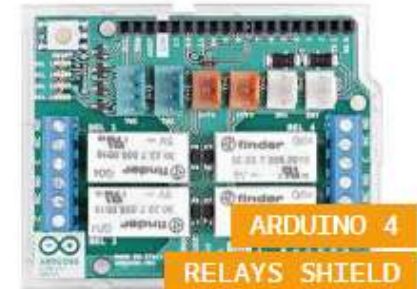
# Enhanced features



PROTO SHIELD



MKR PROTO SHIELD



ARDUINO 4  
RELAYS SHIELD



ARDUINO MEGA  
PROTO SHIELD



MKR RELAY PROTO SHIELD



ARDUINO ISP



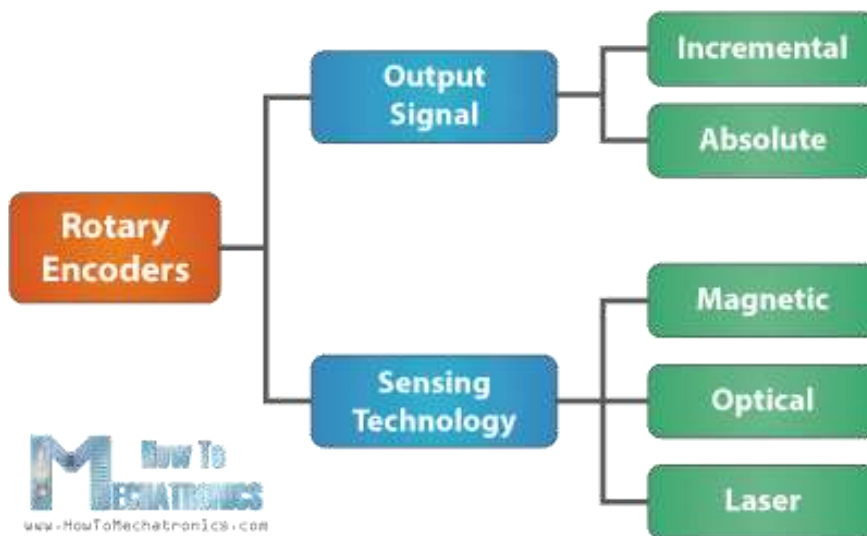
ARDUINO USB2  
SERIAL MICRO



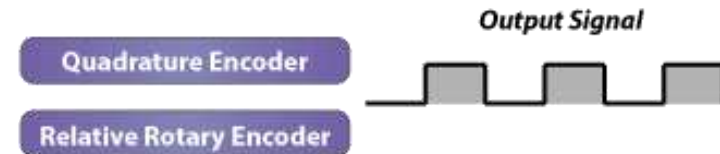
ARDUINO USB2SERIAL  
CONVERTER



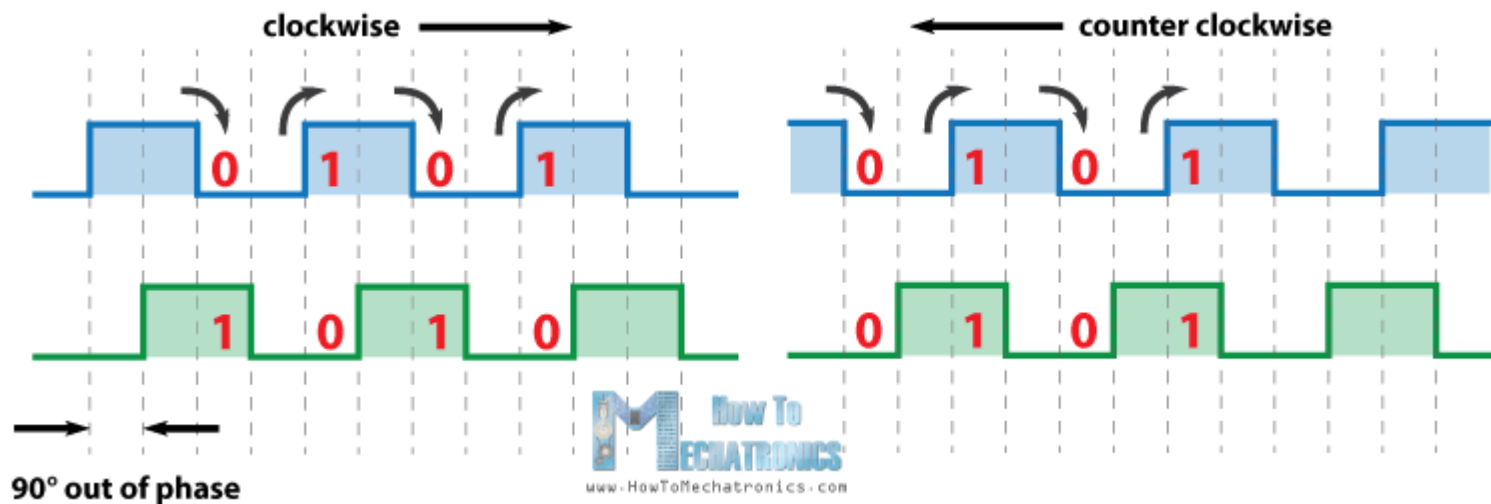
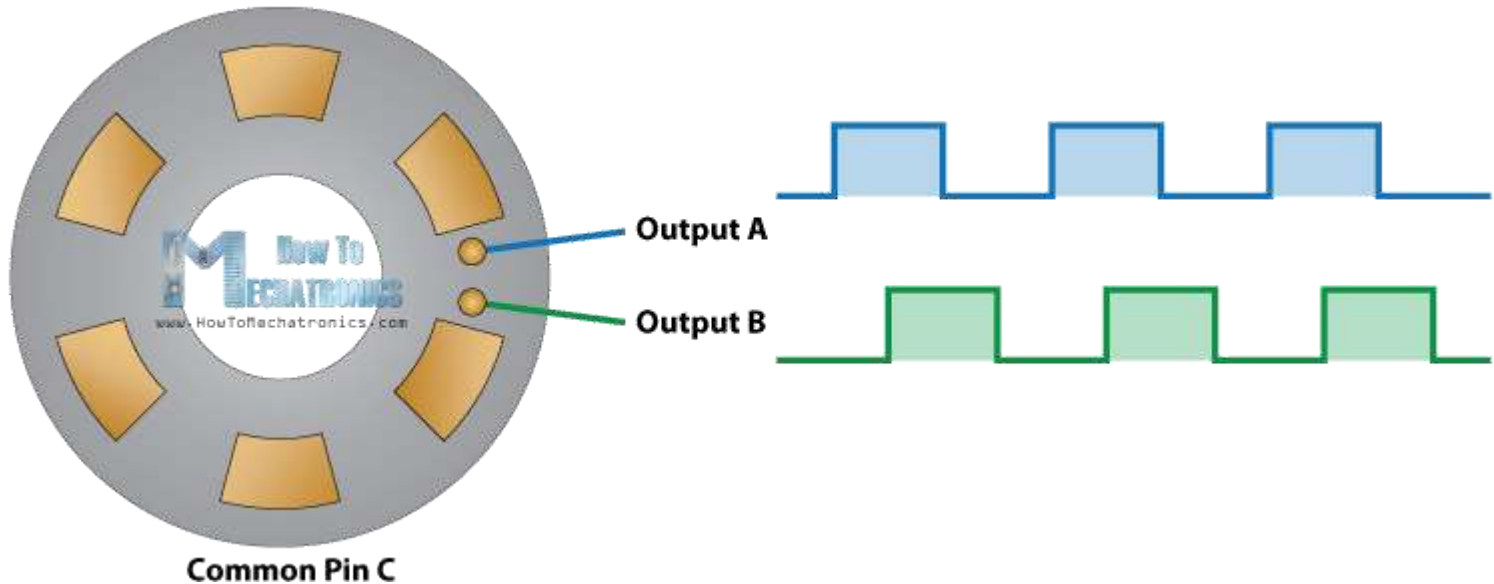
# Rotary encoder



**M** How To  
ELECTRONICS  
www.HowToElectronics.com



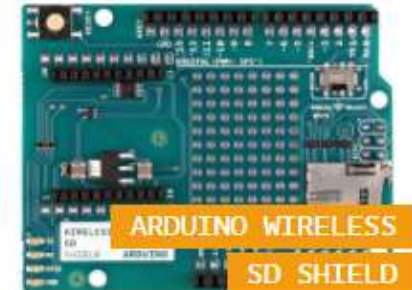
# Rotary encoder operation



# Internet of Things - IOT

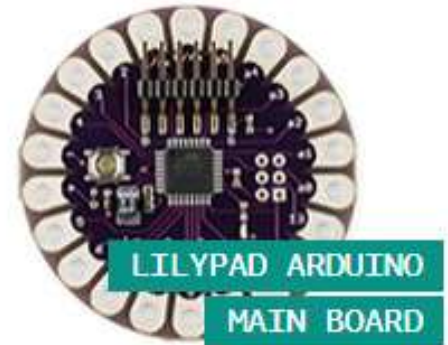


# Internet of Things - IOT





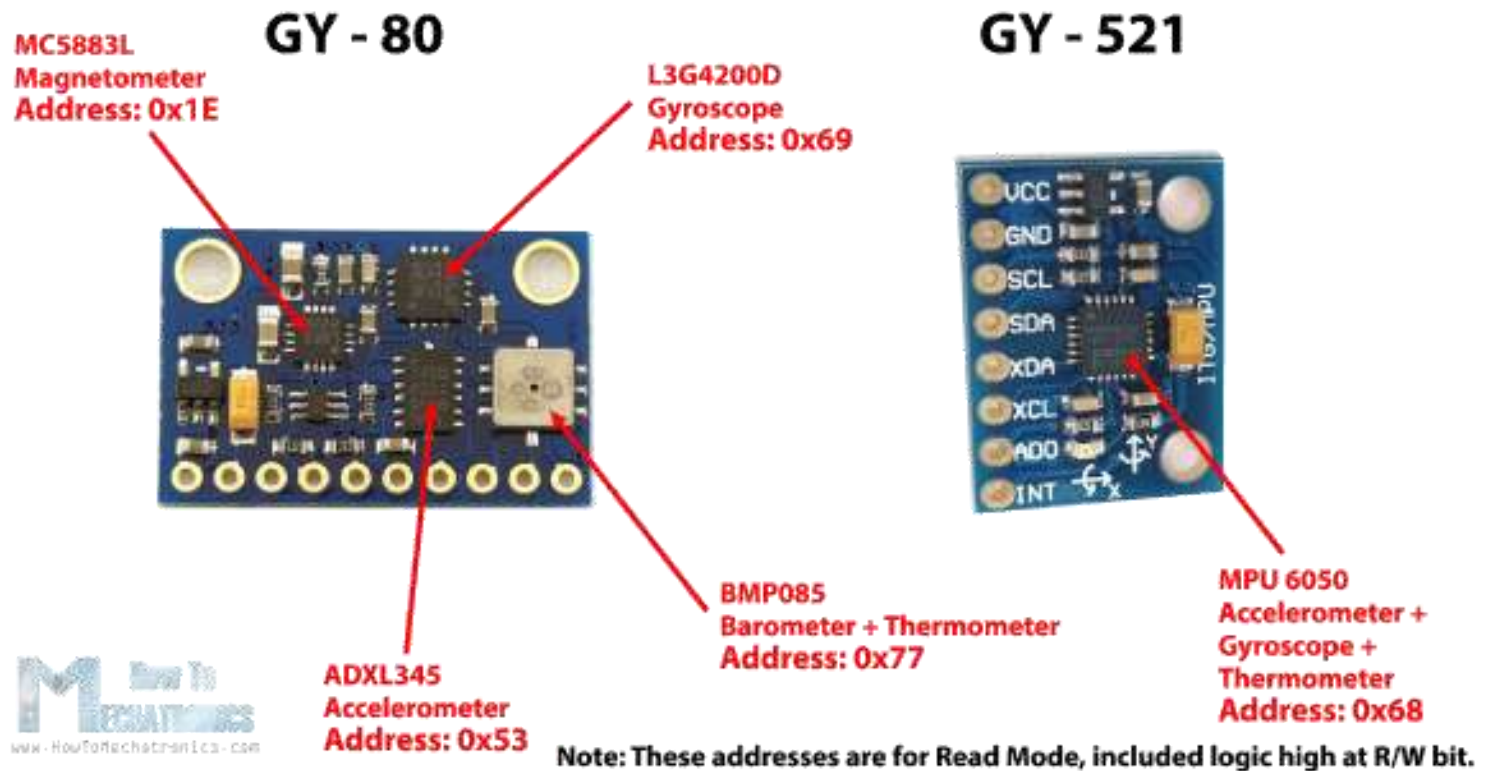
# Wearable



<https://www.arduino.cc/en/Main/Products>

# Arduino boards

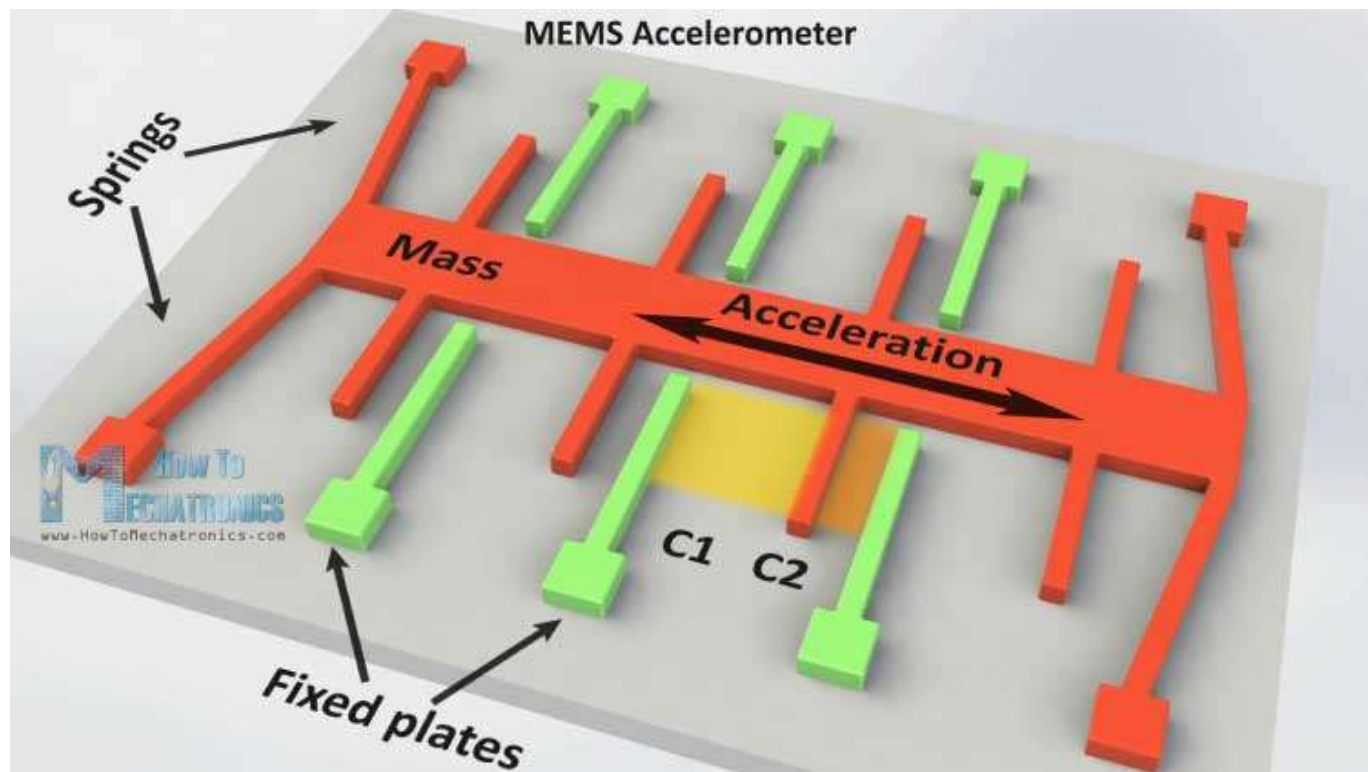
## ARDUINO MICRO





# Sensors

## Micro electro-mechanical systems (MEMS) Accelerometer

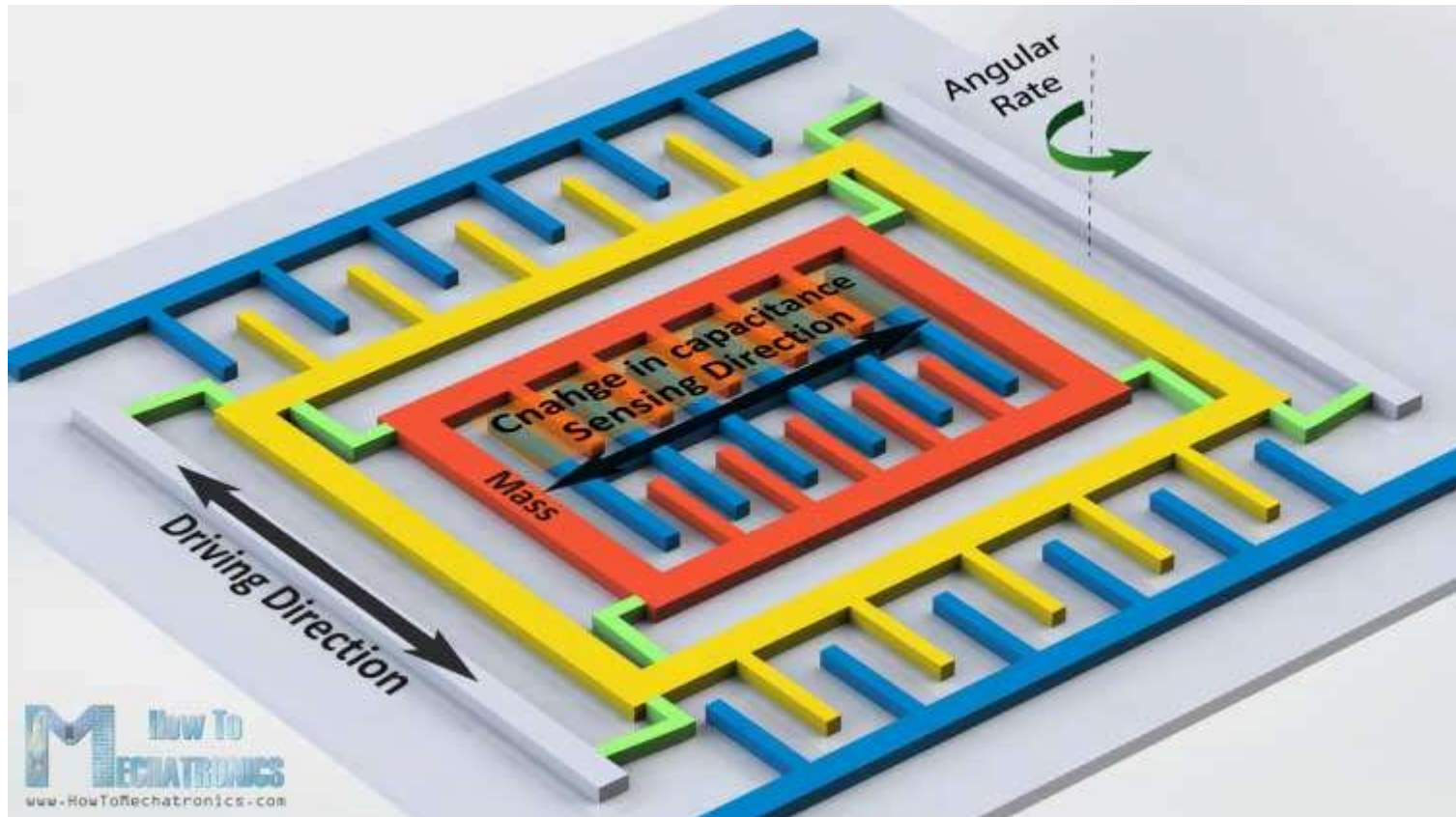


# Sensors

## MEMS gyroscope



Johann Gottlieb Friedrich von Bohnenberger

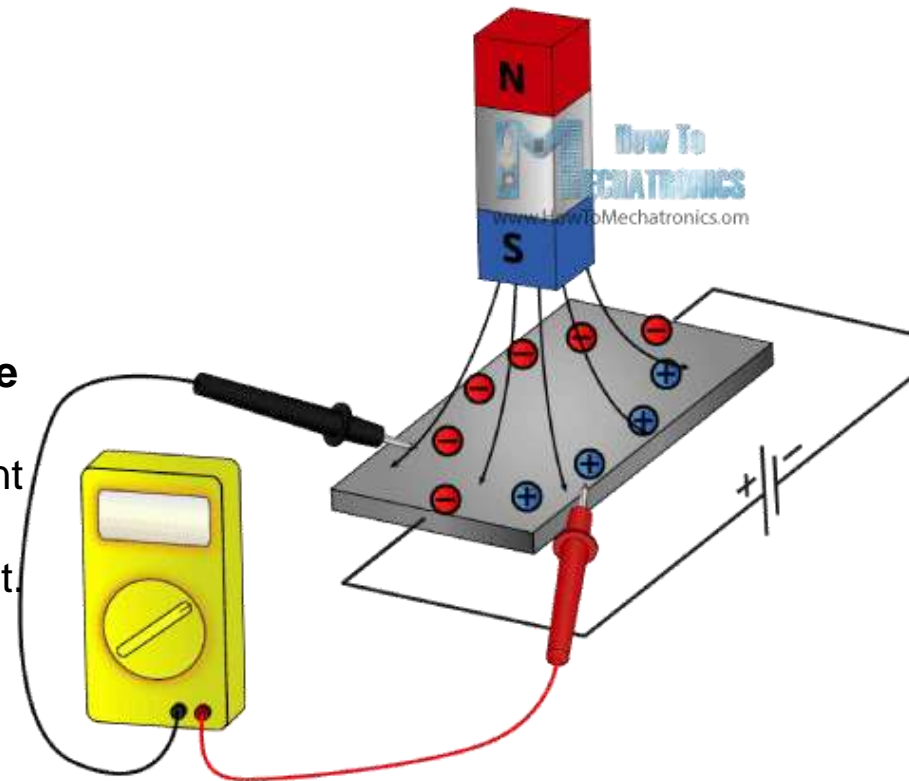
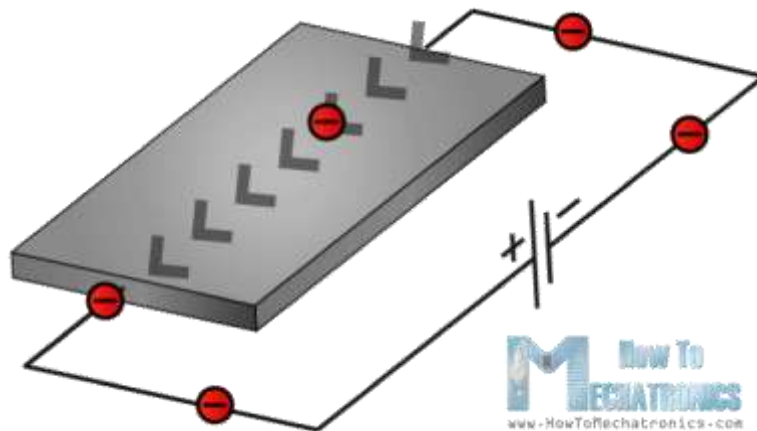


# Sensors

## Magnetic sensors

### Hall Effect

is the **production of a voltage difference** (the Hall voltage) across an electrical conductor, transverse to an electric current in the conductor and to an applied magnetic field perpendicular to the current.



Magneto Resistive Effect is the tendency of a material to change the value of its **electrical resistance** in an externally-applied magnetic field

# Arduino Uno R3



The hardware consists of a simple open source hardware board designed around an 8-bit Atmel AVR microcontroller, or a 32-bit Atmel ARM.

The software consists of a standard programming language compiler and a boot loader that executes on the microcontroller

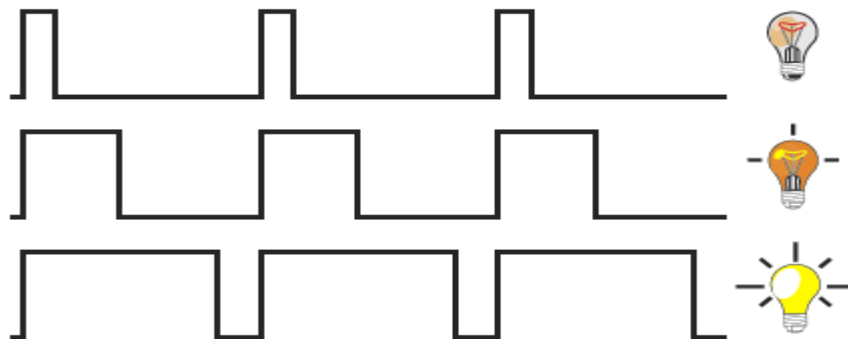
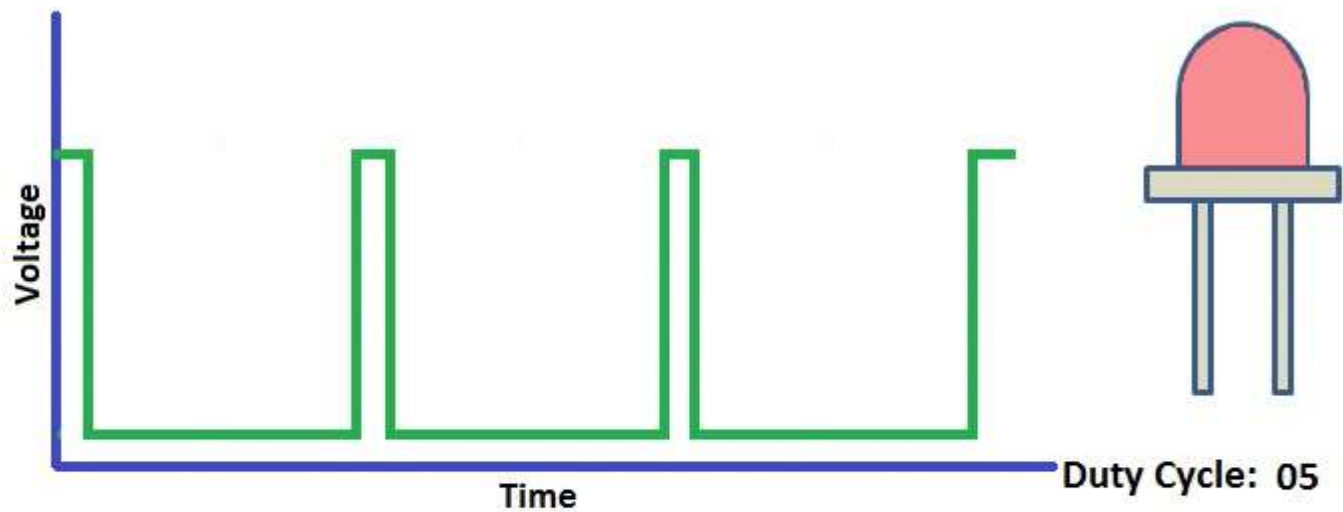
# Arduino Uno R3

- Microcontroller: ATmega328
- Operating Voltage: 5V
- Input Voltage (recommended): 7-12V
- Digital I/O Pins: 14 (6 provide **PWM** output)
- Analog Input Pins: 6
- DC Current per I/O Pin: 40mA/ 3.3V
- Flash Memory: 32 KB (ATmega328)
- SRAM: 2 KB (ATmega328)
- EEPROM: 1 KB (ATmega328)
- Clock Speed: 16 MHz



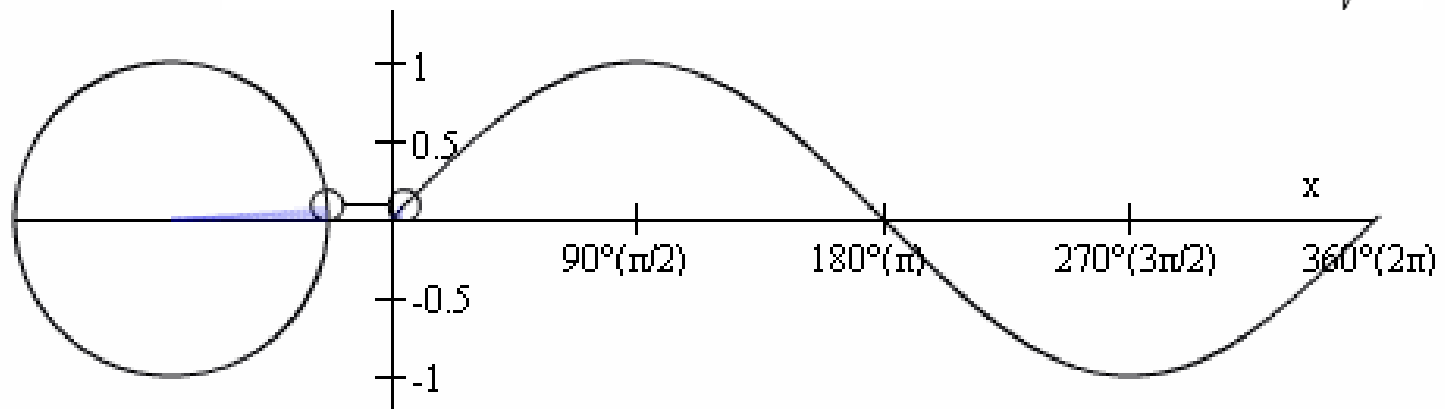
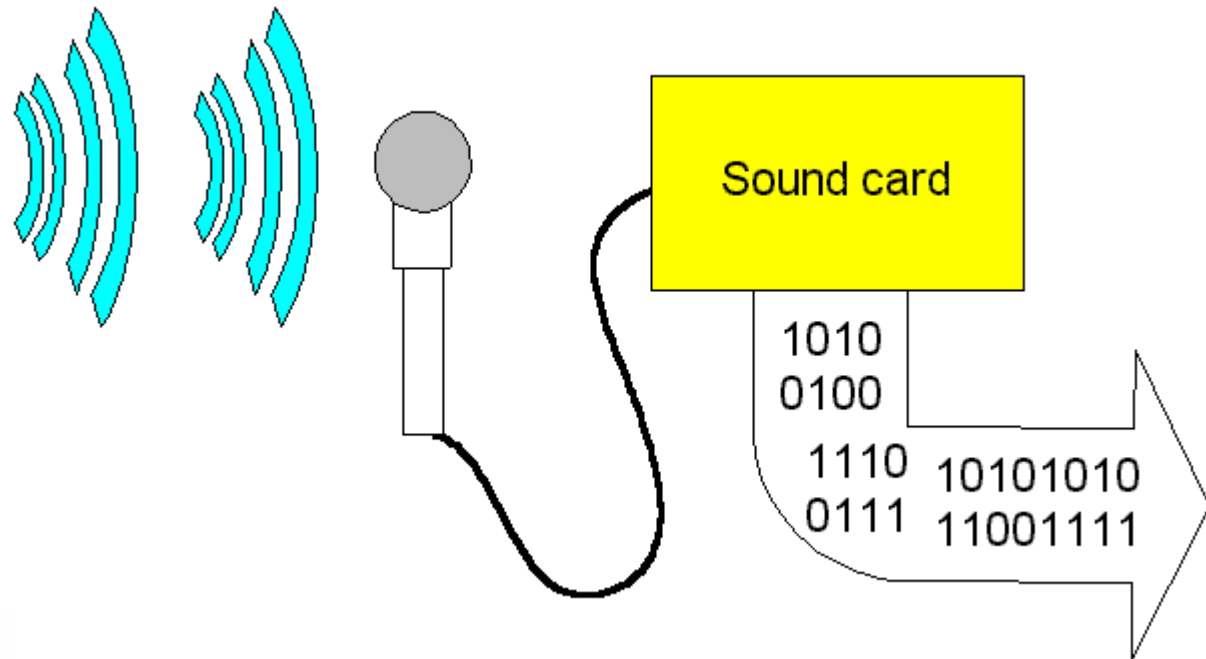
# What mean PWM?

PWM – Pulse With Modulation

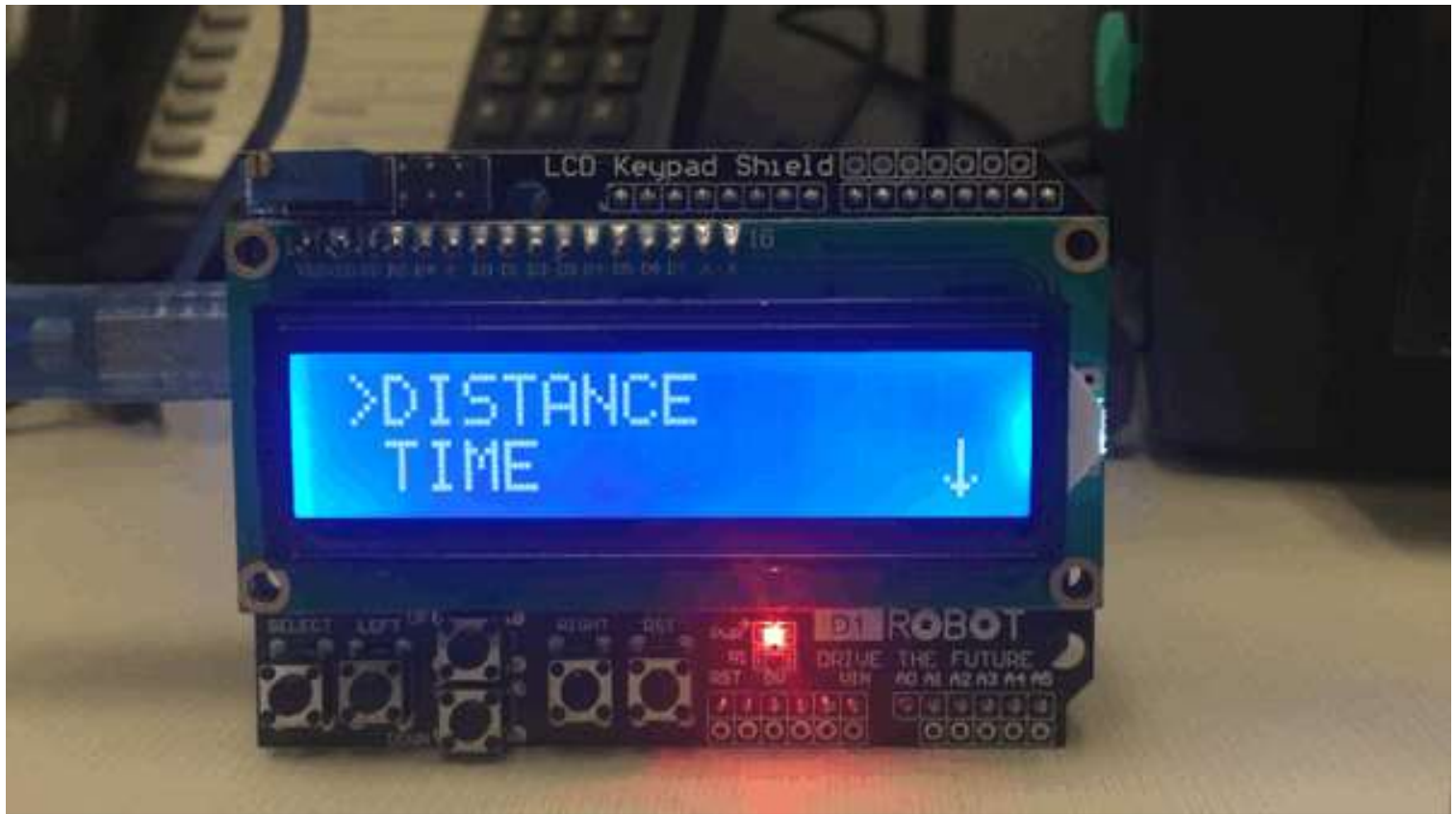




# Analog inputs?



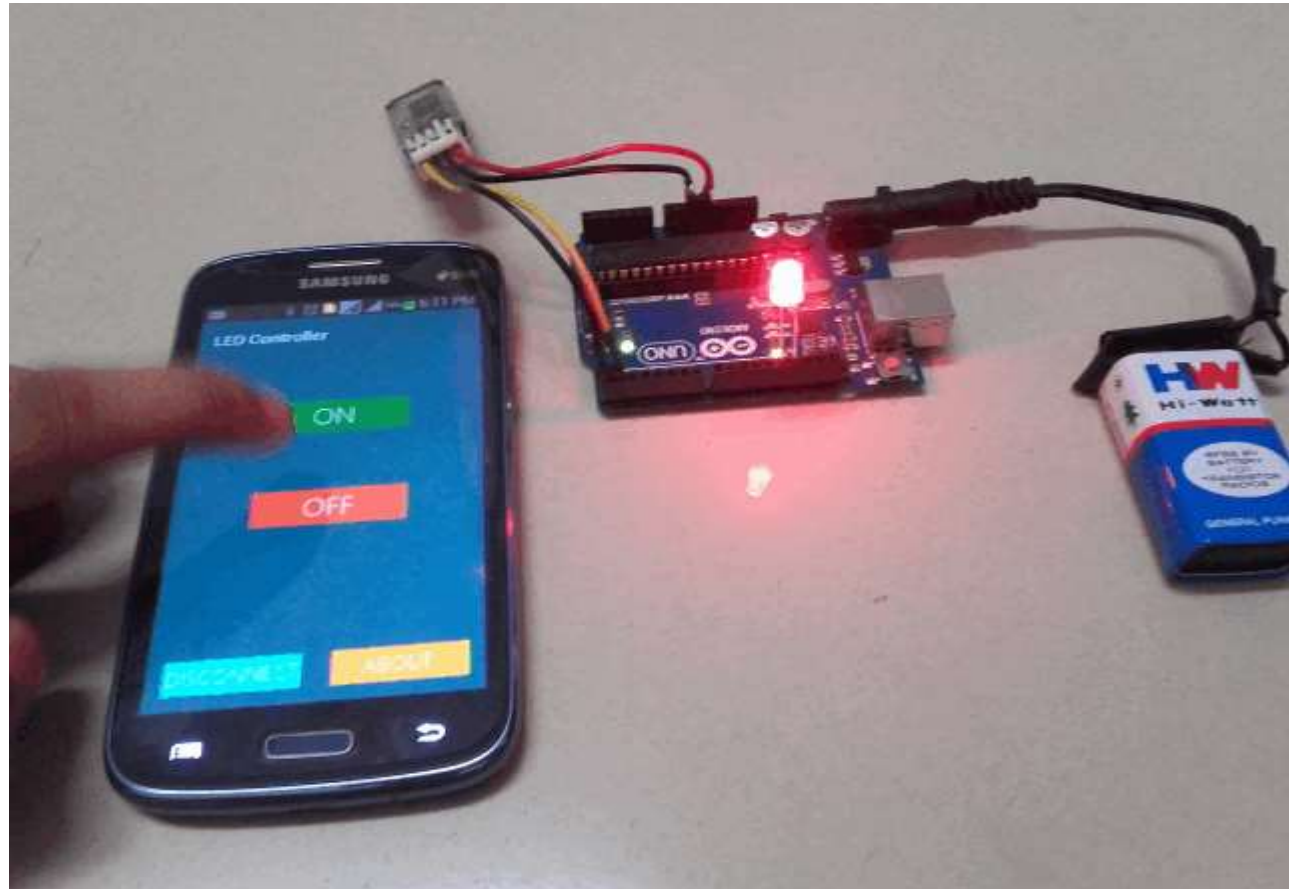
# Applications



LCD display

<http://www.instructables.com/id/Arduino-Uno-Menu-Template/>

# Applications

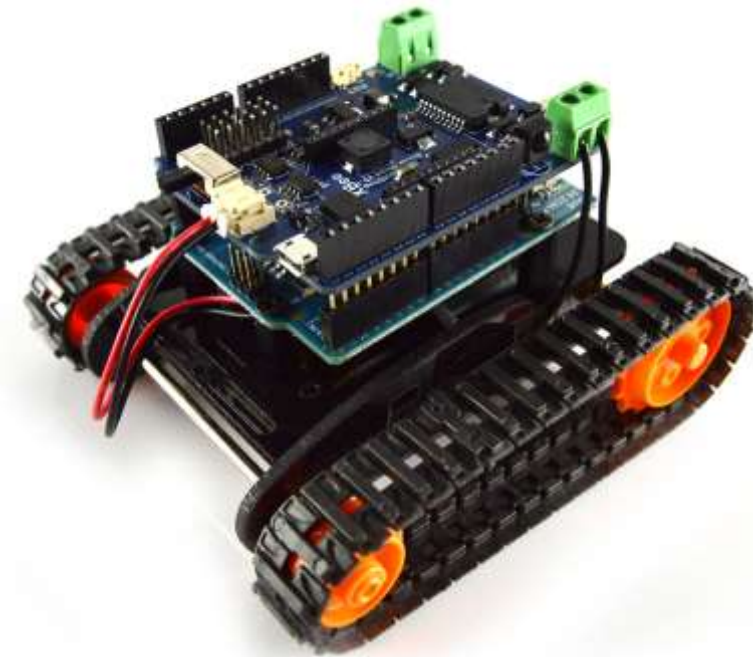


Bluetooth communication

<https://diyhacking.com/arduino-bluetooth-basics/>

# Applications

## Arduino uno radar scope



<https://thesolaruniverse.wordpress.com/2017/03/24/an-arduino-uno-tft-shield-radar-scope/>

# Recommended beginner applications

## Very simple applications

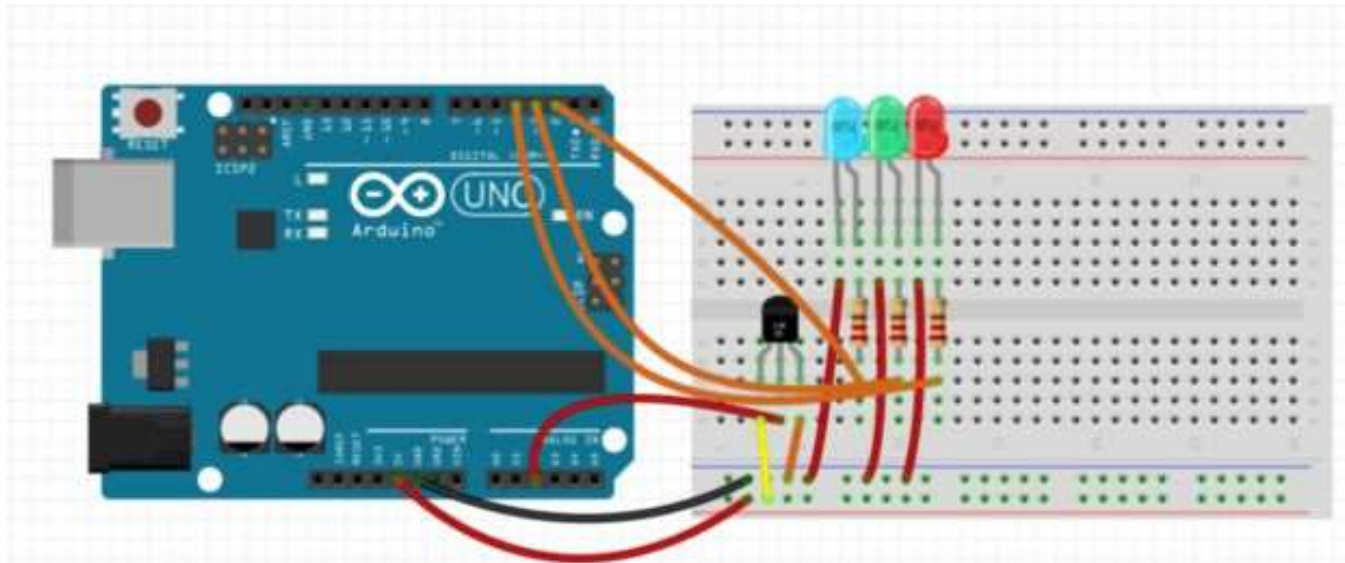
- Turn on of off a LED
- Turn on a LED until a button is pressed
- Cyclically turn on/off a led at each button pressing
- Blink a led with 1Hz frequency
- Blink a LED with 10Hz only when the button is pressed

## Medium difficulty applications

- Using the GPIO interrupts turn on the led at button pressing
- Using timer interrupts blink a led with 10Hz frequency
- Using GPIO and timer interrupts blink the led with 10Hz when the button is pressed and 20Hz when the button is released

# What You Need for a Working System

- Arduino UNO development board
- USB programming cable (A to B)
- 3.9V battery or external power supply (for stand-alone operation)
- Solderless breadboard for external circuits, and 22 g solid wire for connections
- Host PC running



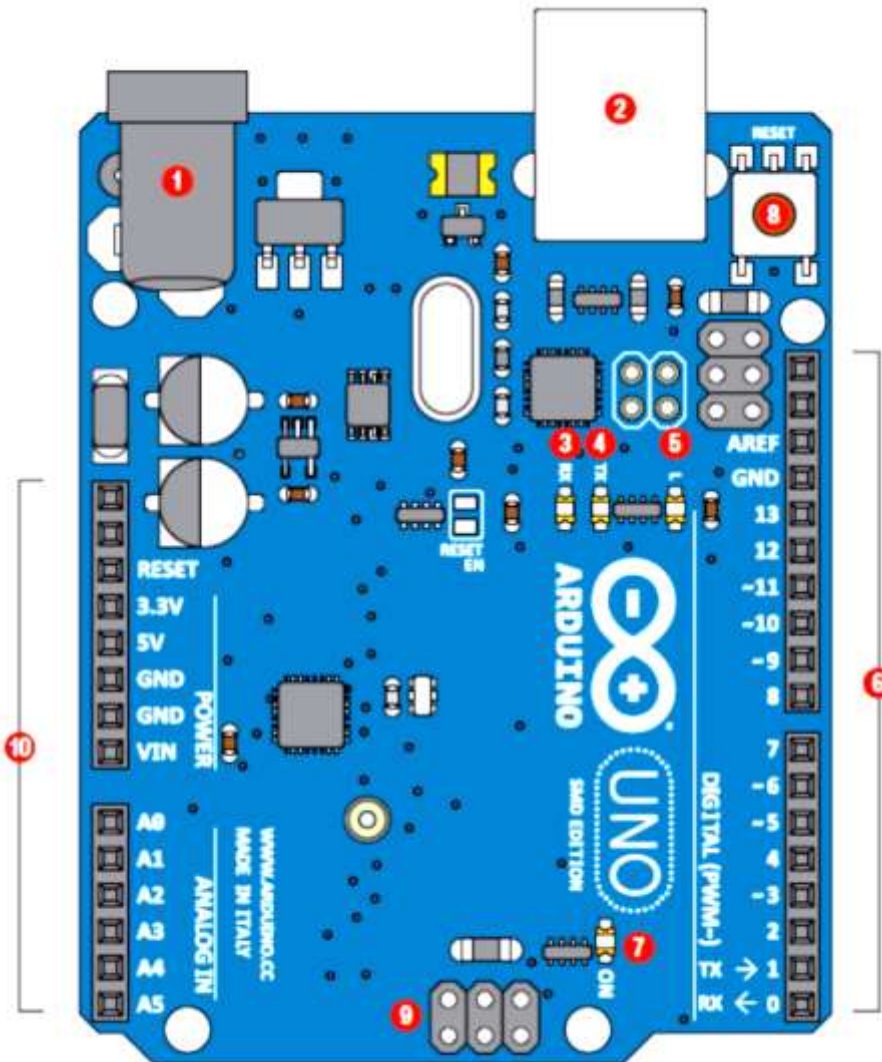


# What You Need for a Working System

- Battery or external power supply (for stand-alone operation)



# Arduino Uno R3



1. Power In
2. Power In USB and communication
3. LED – RX receiving
4. LED – TX transmitting
5. LED – User purpose
6. PINS – User purpose
7. LED – Power indicator
8. Reset Button
9. ICSP connector – upload code
10. 10- User purpose

# Arduino Uno R3



The header pins are one of the most important parts for putting our example circuits together. Take a moment and locate the input/output ports of your Arduino Uno.

10

RFU			
IOREF			
Reset		RESET	
Power Out		3.3V	
Power Out		5V	
Ground		GND	
Ground		GND	
Power In		VIN	
			POWER
Analog		A0	
Analog		A1	
Analog		A2	
Analog		A3	
Analog		A4	
Analog		A5	
			ANALOG IN

AREF

GND

13

12

~11

~10

~9

8

7

~6

~5

4

~3

2

TX → 1

RX ← 0

DIGITAL (PWM~)

SCL

SDA

AREf

Ground

Digital

Digital

Digital

Digital

Digital

Digital

Digital

Digital

Digital

Digital

Digital

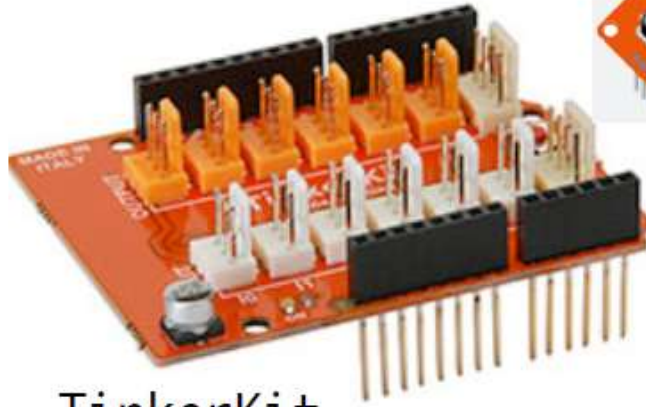
Digital

TX - Out

RX - In

6

Alt 1 (no wiring)



TinkerKit  
Sensor Shield

Alt 2 (wiring)

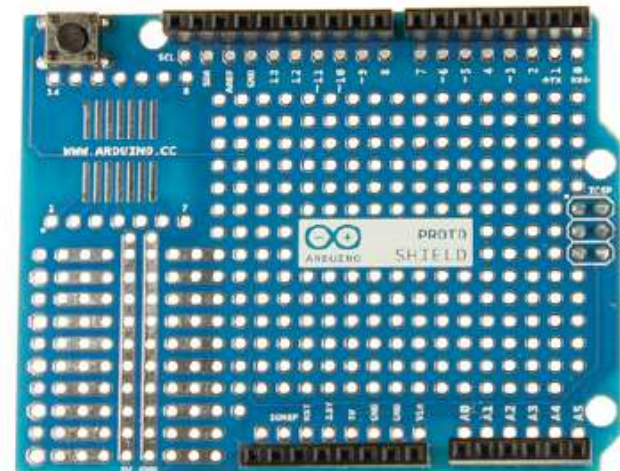


Breadboard

Alt 3 (soldering)



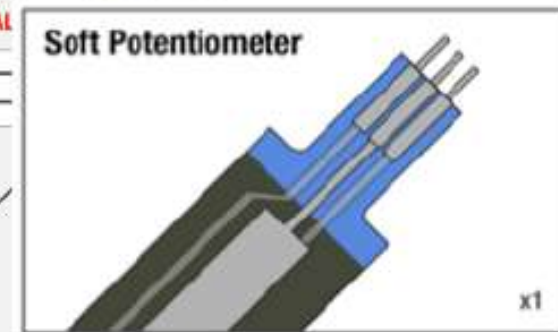
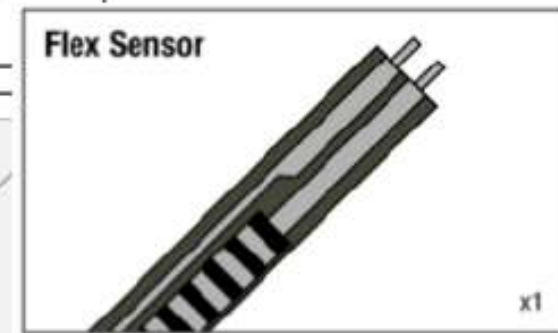
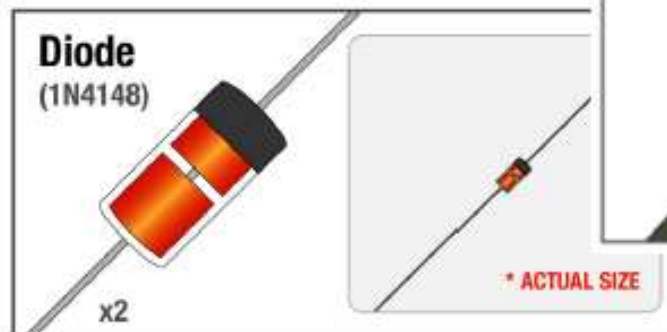
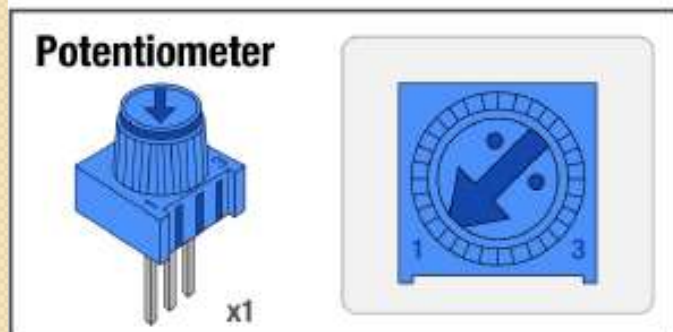
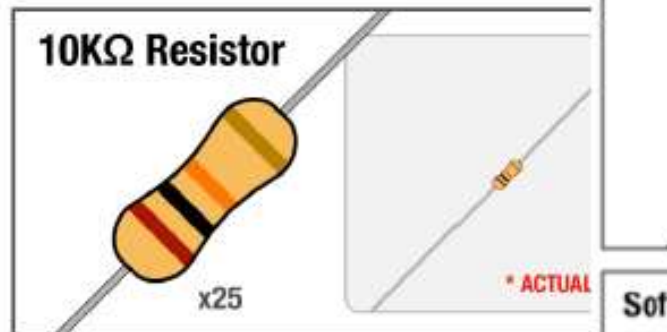
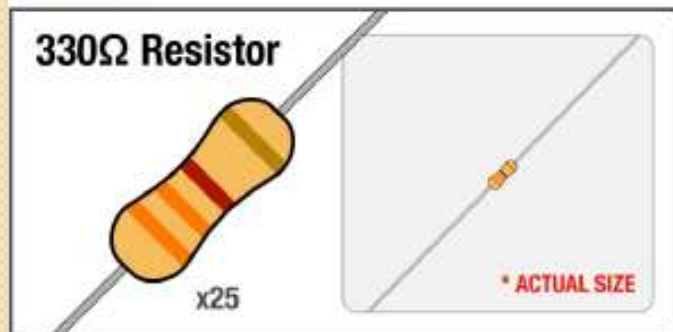
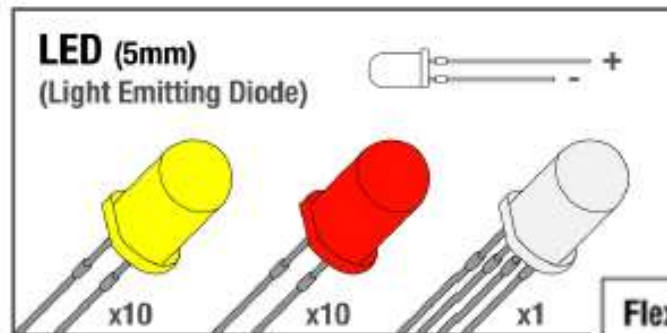
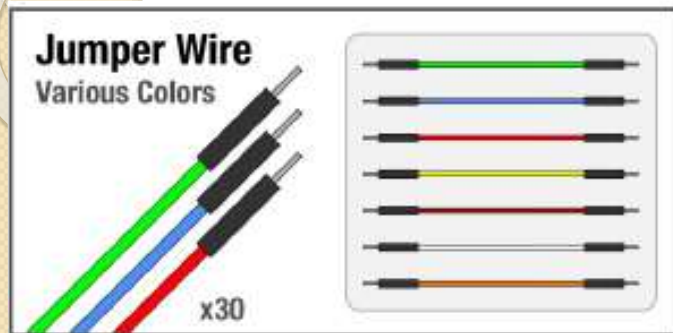
Arduino UNO



Arduino Proto Shield

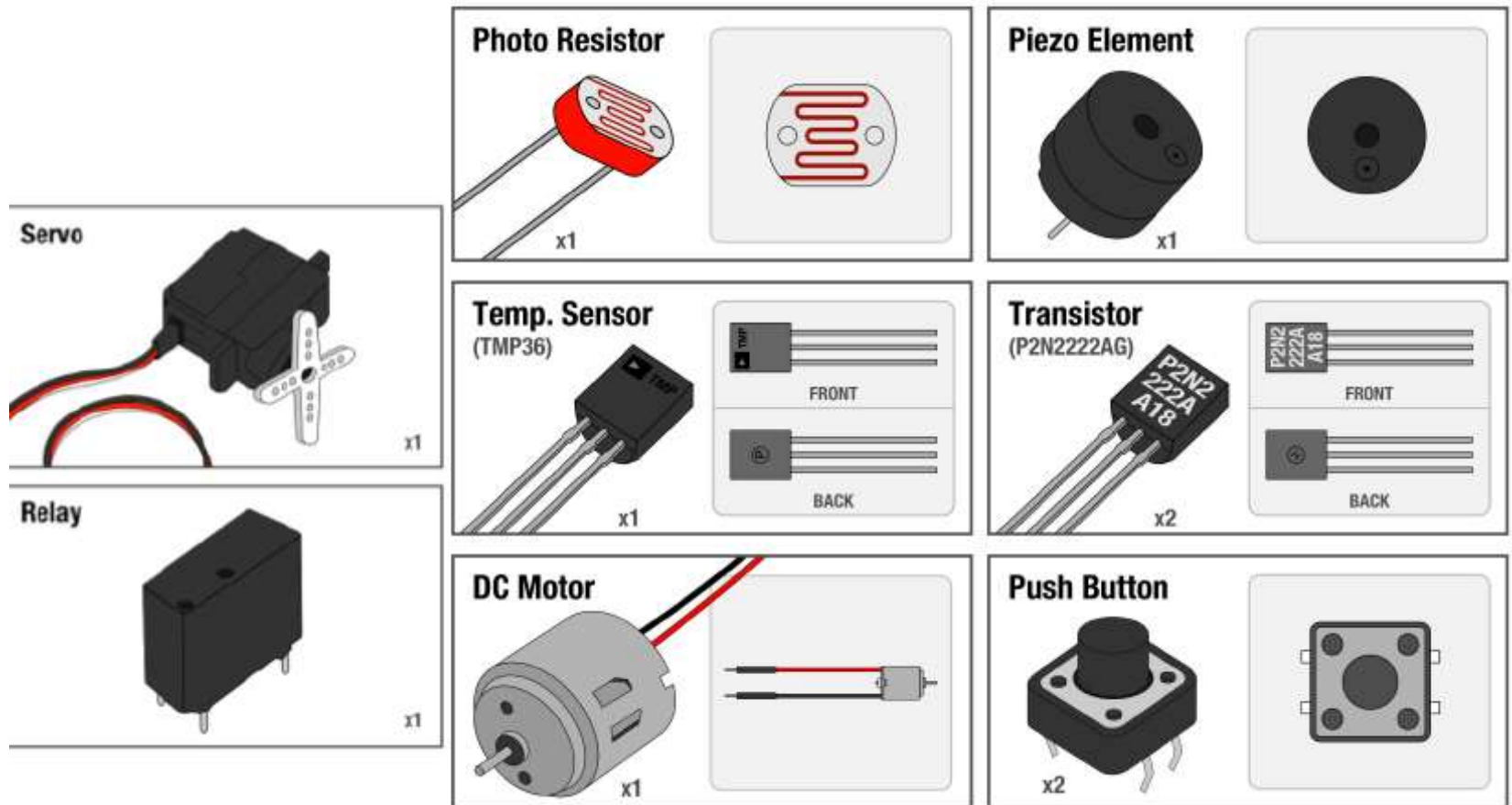


# Arduino Uno R3 Connexions

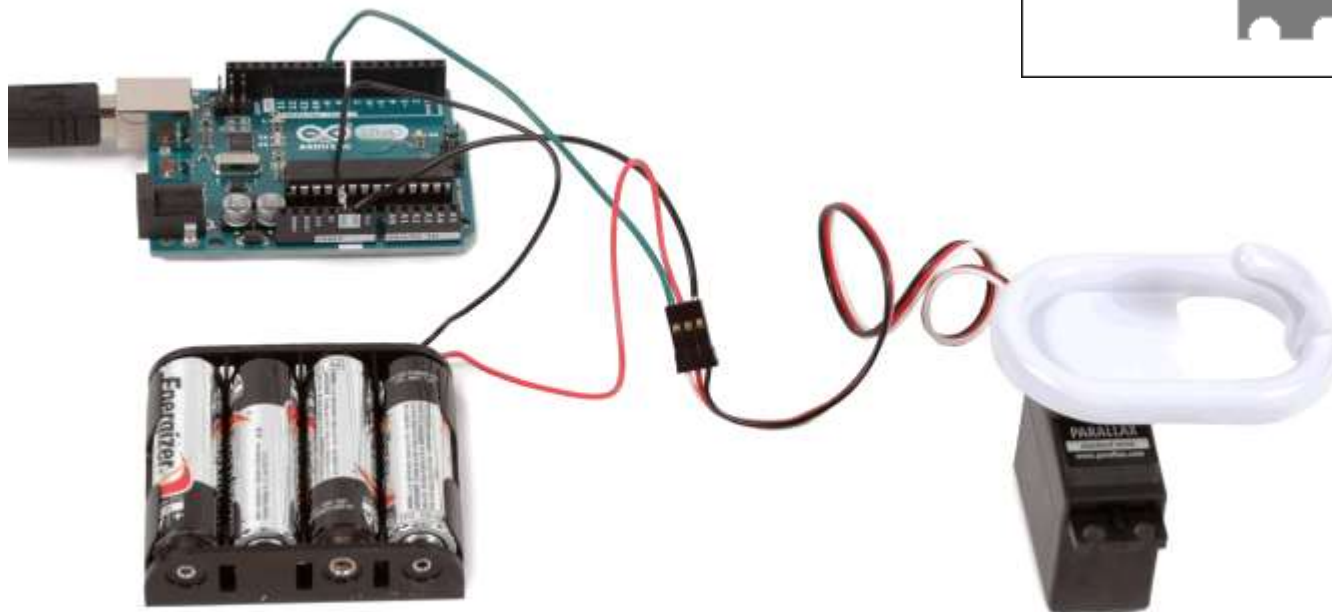
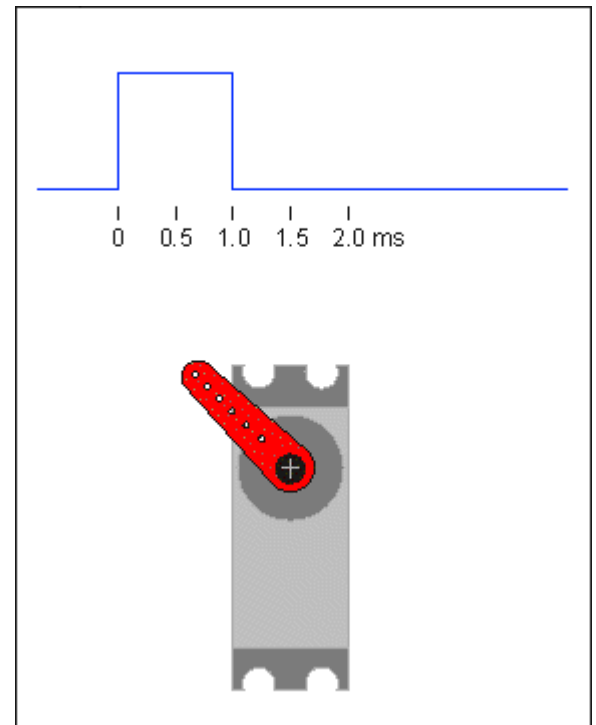




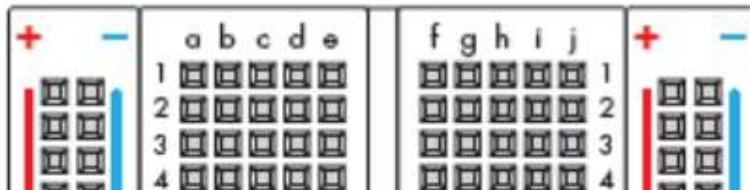
# Arduino Uno R3 Connexions



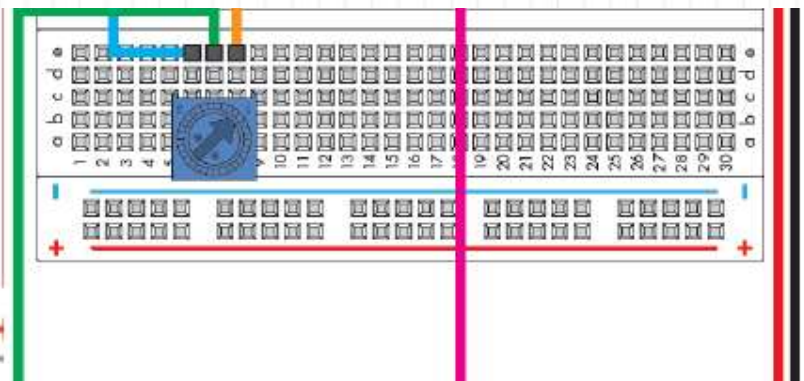
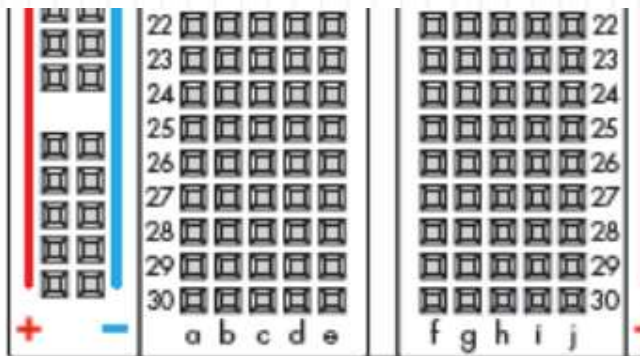
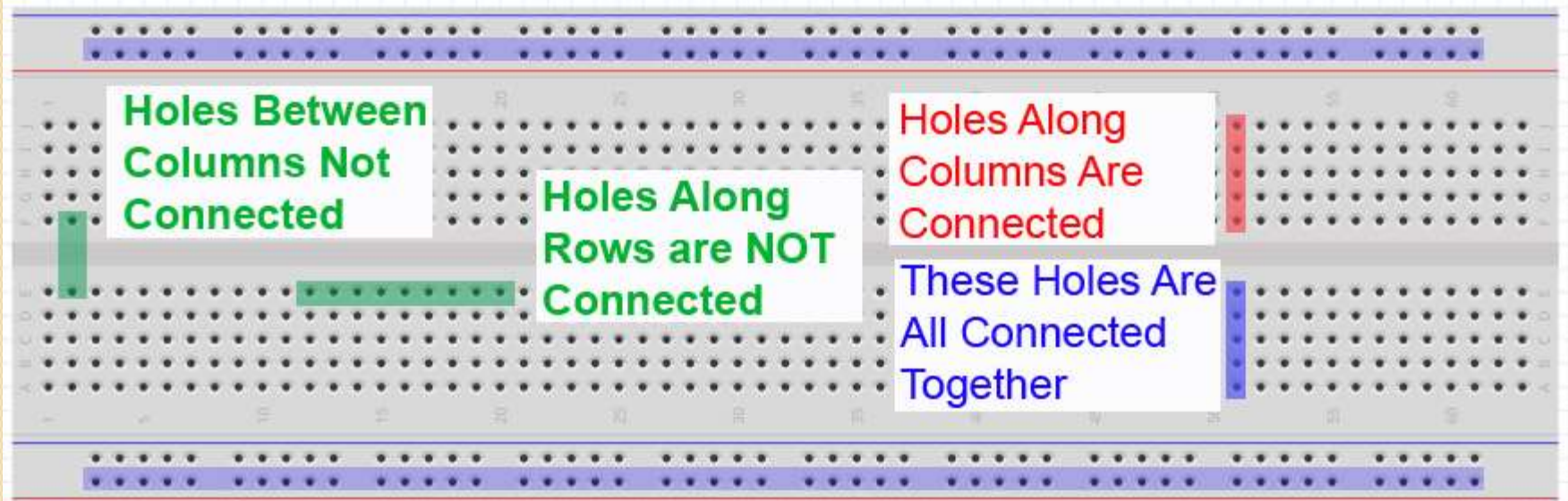
# Servo motor



# Arduino Uno R3 Breadboard



A breadboard is used

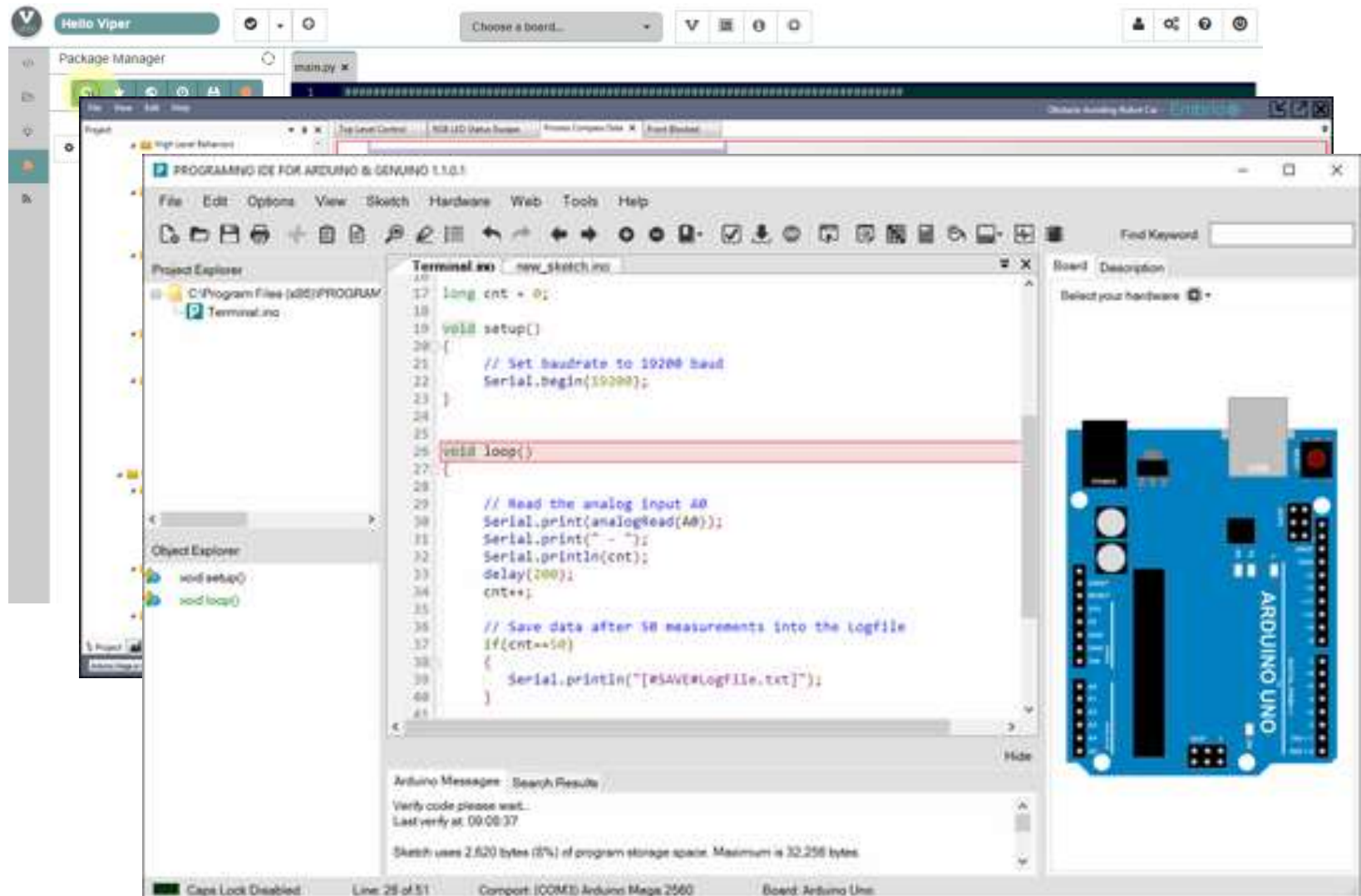


# Alternative IDE

PROGRAMINO IDE

Embrio

Zerynth



# IDE (Integrated Development Environment)

- Software application that provides comprehensive facilities to computer programmers for software development.
- Advantages:
  - Increased productivity
  - Feedback on syntax errors
  - Hotkeys
- Consists of :
  - source code editor,
  - build automation tools
  - debugger.



# Arduino IDE/ Scketch



## ARDUINO 1.8.5

The open-source Arduino Software (IDE) makes it easy to write code and upload it to the board. It runs on Windows, Mac OS X, and Linux. The environment is written in Java and based on Processing and other open-source software.

This software can be used with any Arduino board. Refer to the [Getting Started](#) page for Installation instructions.

**Windows** Installer

**Windows** ZIP file for non admin install

**Windows app** 

**Mac OS X** 10.7 Lion or newer

**Linux** 32 bits

**Linux** 64 bits

**Linux** ARM

[Release Notes](#)

[Source Code](#)

[Checksums \(sha512\)](#)

The Arduino Software (IDE) allows you to write programs and upload them to your board.

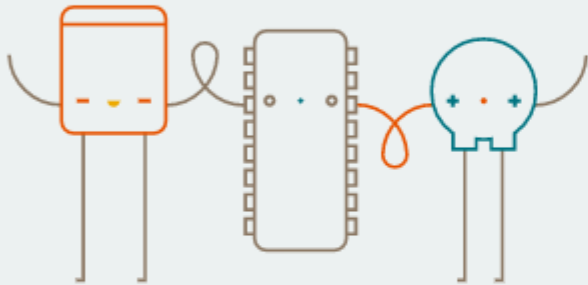
<https://www.arduino.cc/en/Main/Software>

[http://www.w3ii.com/ro/arduino/arduino\\_installation.html](http://www.w3ii.com/ro/arduino/arduino_installation.html)

# Arduino IDE/ Scketch

## Contribute to the Arduino Software

Consider supporting the Arduino Software by contributing to its development. (US tax payers, please note this contribution is not tax deductible). [Learn more on how your contribution will be used.](#)



SINCE MARCH 2015, THE ARDUINO IDE HAS BEEN DOWNLOADED

**19,380,191** TIMES. (IMPRESSIVE!) NO LONGER JUST FOR ARDUINO AND GENUINO BOARDS, HUNDREDS OF COMPANIES AROUND THE WORLD ARE USING THE IDE TO PROGRAM THEIR DEVICES, INCLUDING COMPATIBLES, CLONES, AND EVEN COUNTERFEITS. HELP ACCELERATE ITS DEVELOPMENT WITH A SMALL CONTRIBUTION! REMEMBER: OPEN SOURCE IS LOVE!

\$3

\$5

\$10

\$25

\$50

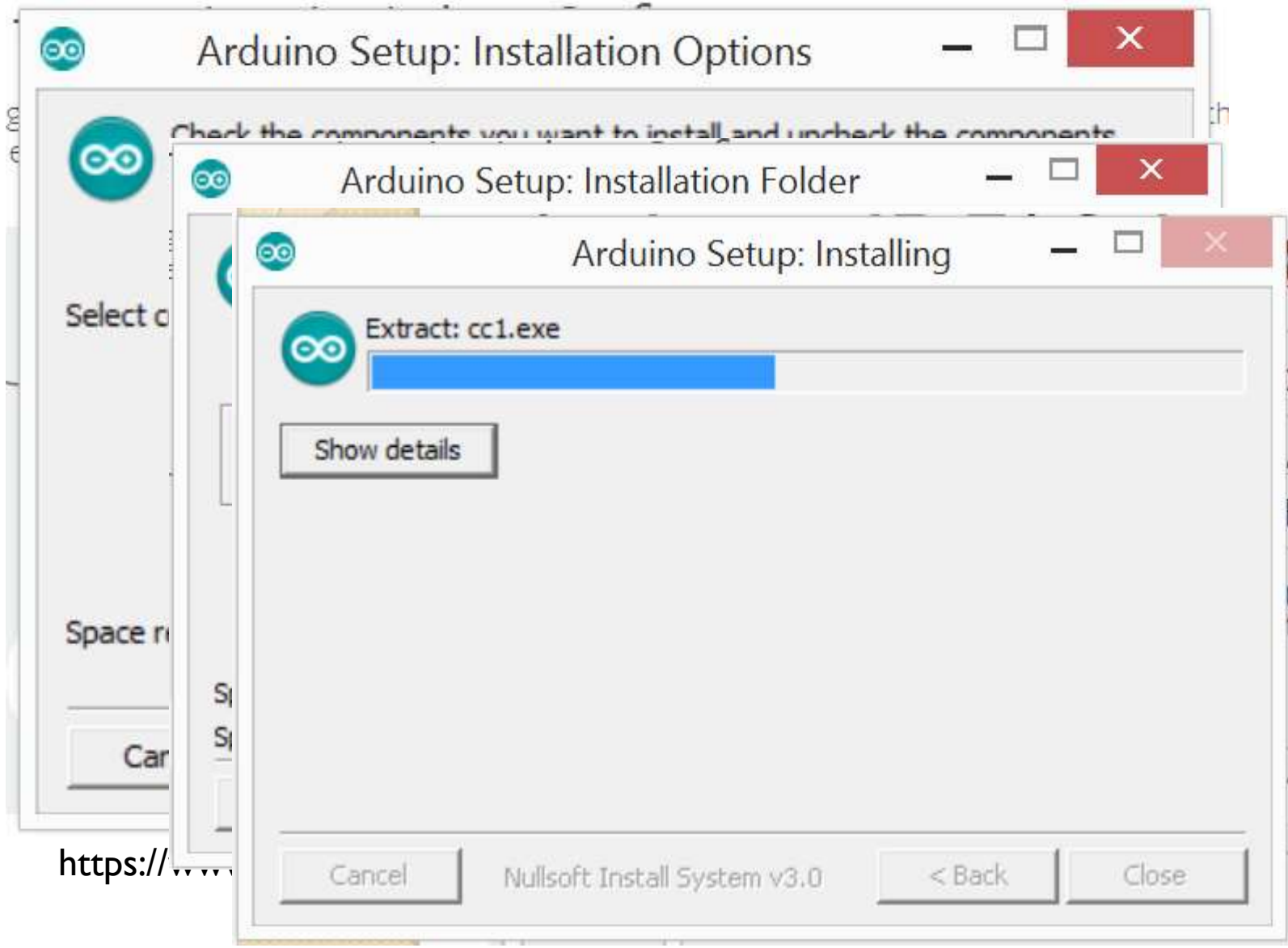
OTHER

JUST DOWNLOAD

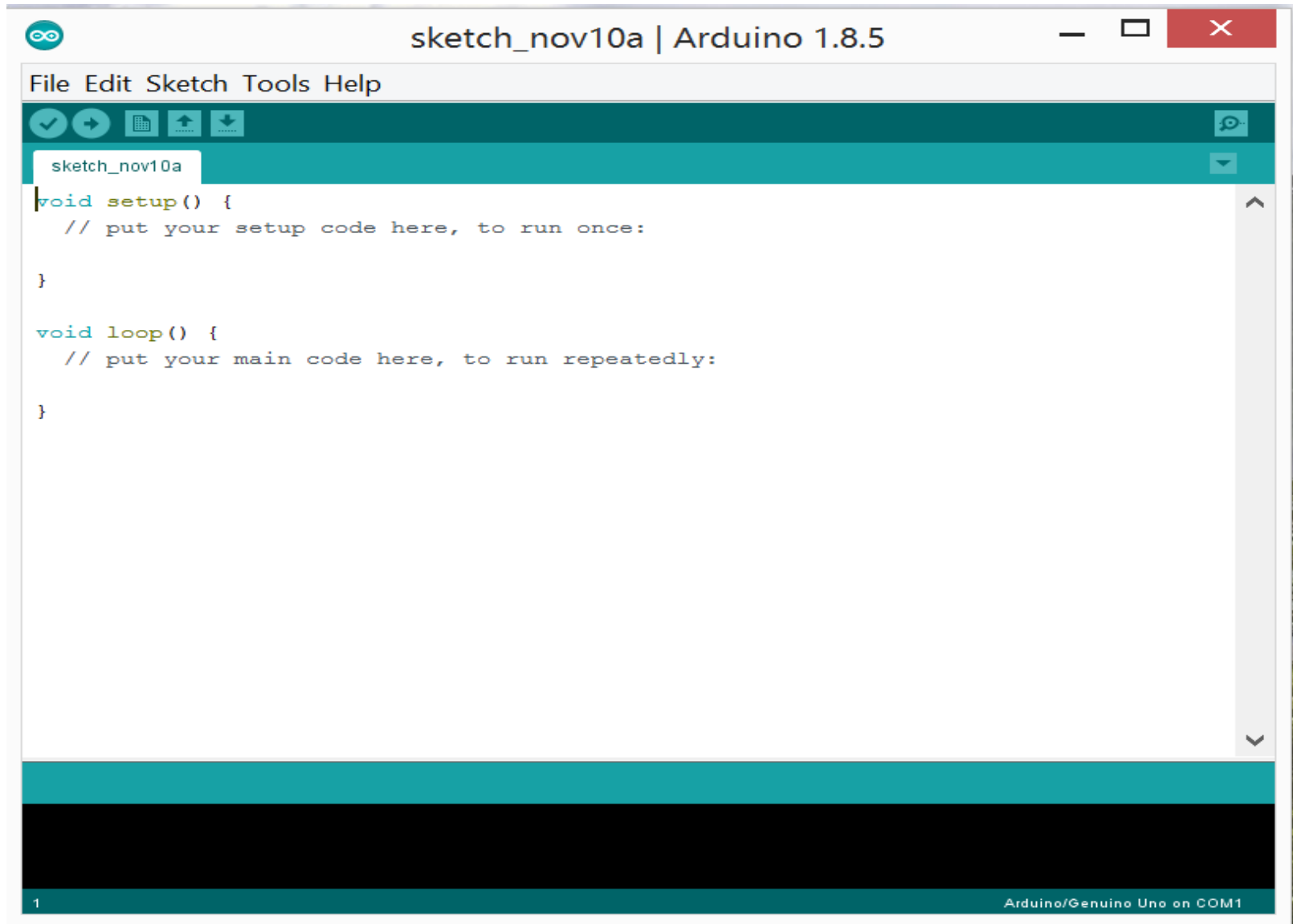
CONTRIBUTE & DOWNLOAD

<https://www.arduino.cc/en/Main/Software>

# Arduino IDE/ Scketch



# Arduino IDE/ Scketch



# File

- ***New***

Creates a new instance of the editor with the same structure of a sketch already in the IDE.

- ***Open***

Allows to load a sketch file from the file browser and folders.

- ***Open Recent***

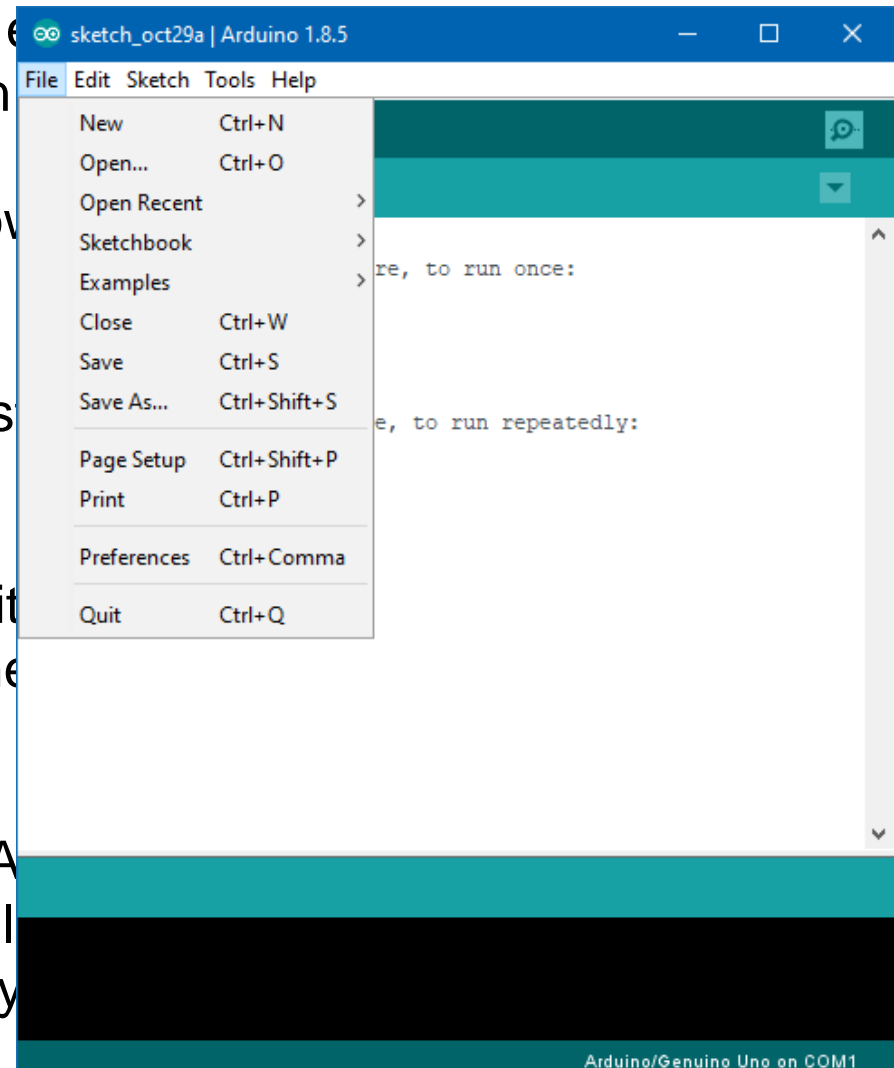
Provides a short list of the most recently opened sketches.

- ***Sketchbook***

Shows the current sketches with the Sketchbook icon. Clicking on any name opens the sketch in the editor instance.

- ***Examples***

Any example provided by the Arduino IDE shows up in this menu item. All examples are organized in a tree that allows easy access by clicking on the example name.





# File

- **Close**

Closes the instance of the Arduino Software from which it is clicked.

- **Save**

Saves the sketch with the current name. If the file hasn't been named before, a name will be provided in a "Save as.." window.

- **Save as...**

Allows to save the current sketch with a different name.

- **Print**

Sends the current sketch to the printer according to the settings defined in Page Setup.

- **Preferences**

Opens the Preferences window where some settings of the IDE may be customized, as the language of the IDE interface.

- **Quit**

Closes all IDE windows. The same sketches open when Quit was chosen will be automatically reopened the next time you start the IDE.

# Edit

- **Undo/Redo**

Goes back of one or more steps. If you go back, you may go forward with Redo.

- **Cut**

Removes the selected text from the sketch and puts it on the clipboard.

- **Copy**

Duplicates the selected text from the sketch to the clipboard.

- **Copy for Forum**

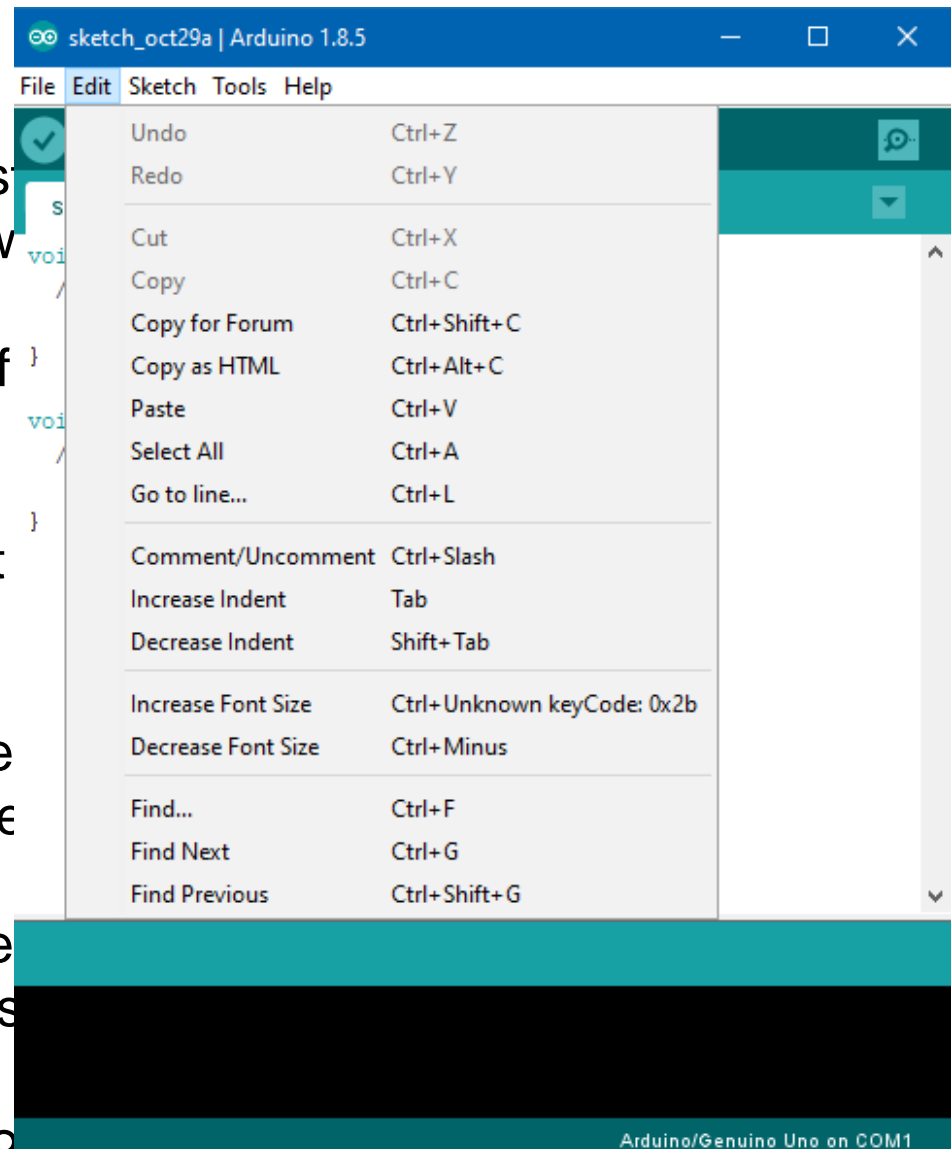
Copies the code of your sketch to the clipboard in a format suitable for posting to the forum, complete with code tags.

- **Copy as HTML**

Copies the code of your sketch to the clipboard in a format suitable for embedding in web pages.

- **Paste**

Puts the contents of the clipboard into the sketch at the current cursor position.



# Edit

- **Select All**

Selects and highlights the whole content of the editor.

- **Comment/Uncomment**

Puts or removes the // comment marker at the beginning of each selected line.

- **Increase/Decrease Indent**

Adds or subtracts a space at the beginning of each selected line, moving the text one space on the right or eliminating a space at the beginning.

- **Find**

Opens the Find and Replace window where you can specify text to search inside the current sketch according to several options.

- **Find Next**

Highlights the next occurrence - if any - of the string specified as the search item in the Find window, relative to the cursor position.

- **Find Previous**

Highlights the previous occurrence - if any - of the string specified as the search item in the Find window relative to the cursor position.

# Sketch

- **Verify/Compile**

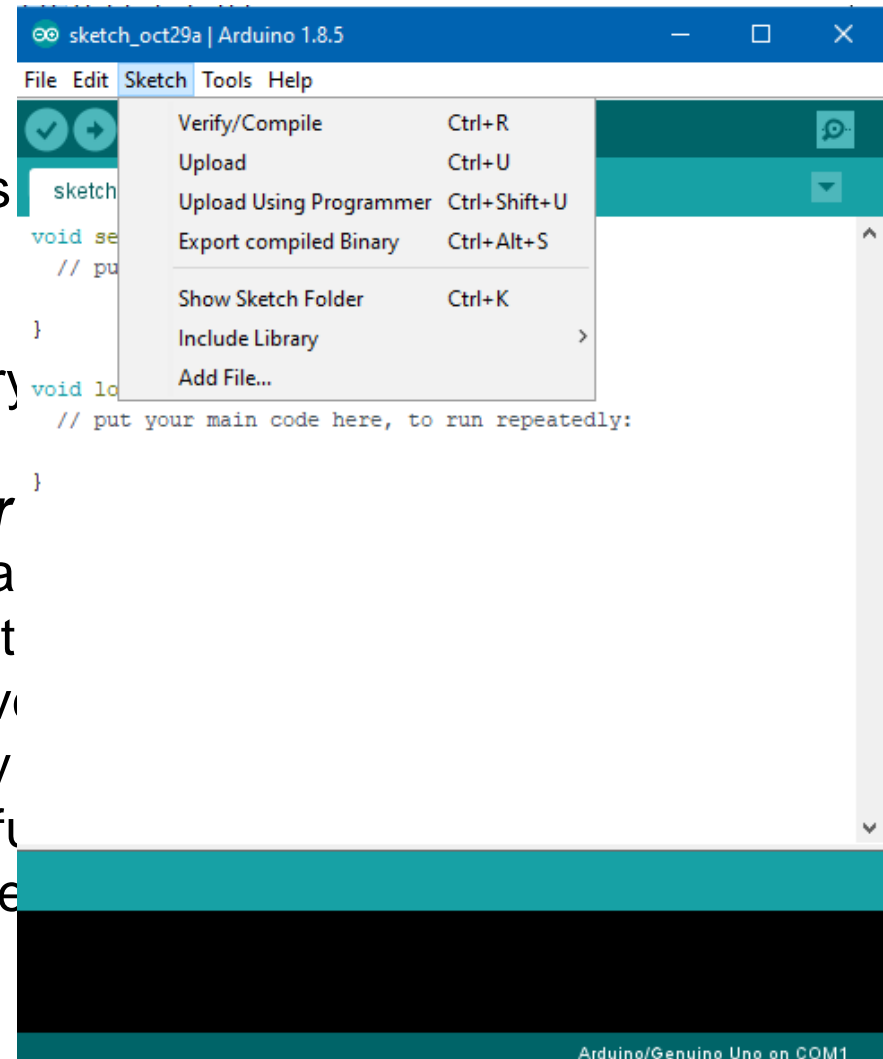
Checks your sketch for errors  
usage for code and variables

- **Upload**

Compiles and loads the binary  
through the configured Port.

- **Upload Using Programmer**

This will overwrite the bootloa  
use Tools > Burn Bootloader t  
USB serial port again. Howev  
capacity of the Flash memory  
command will NOT burn the fu  
*Bootloader* command must be



# Sketch

- ***Export Compiled Binary***

Saves a .hex file that may be kept as archive or sent to the board using other tools.

- ***Show Sketch Folder***

Opens the current sketch folder.

- ***Include Library***

Adds a library to your sketch by inserting #include statements at the start of your code. For more details, see [libraries](#) below. Additionally, from this menu item you can access the Library Manager and import new libraries from .zip files.

- ***Add File...***

Adds a source file to the sketch (it will be copied from its current location). The new file appears in a new tab in the sketch window. Files can be removed from the sketch using the tab menu accessible clicking on the small triangle icon below the serial monitor one on the right side of the toolbar.



# Tools

- ***Auto Format***

This formats your code nice closing curly braces line up closing curly braces are indented more.

- ***Archive Sketch***

Archives a copy of the current sketch placed in the same directory.

- ***Fix Encoding & Reload***

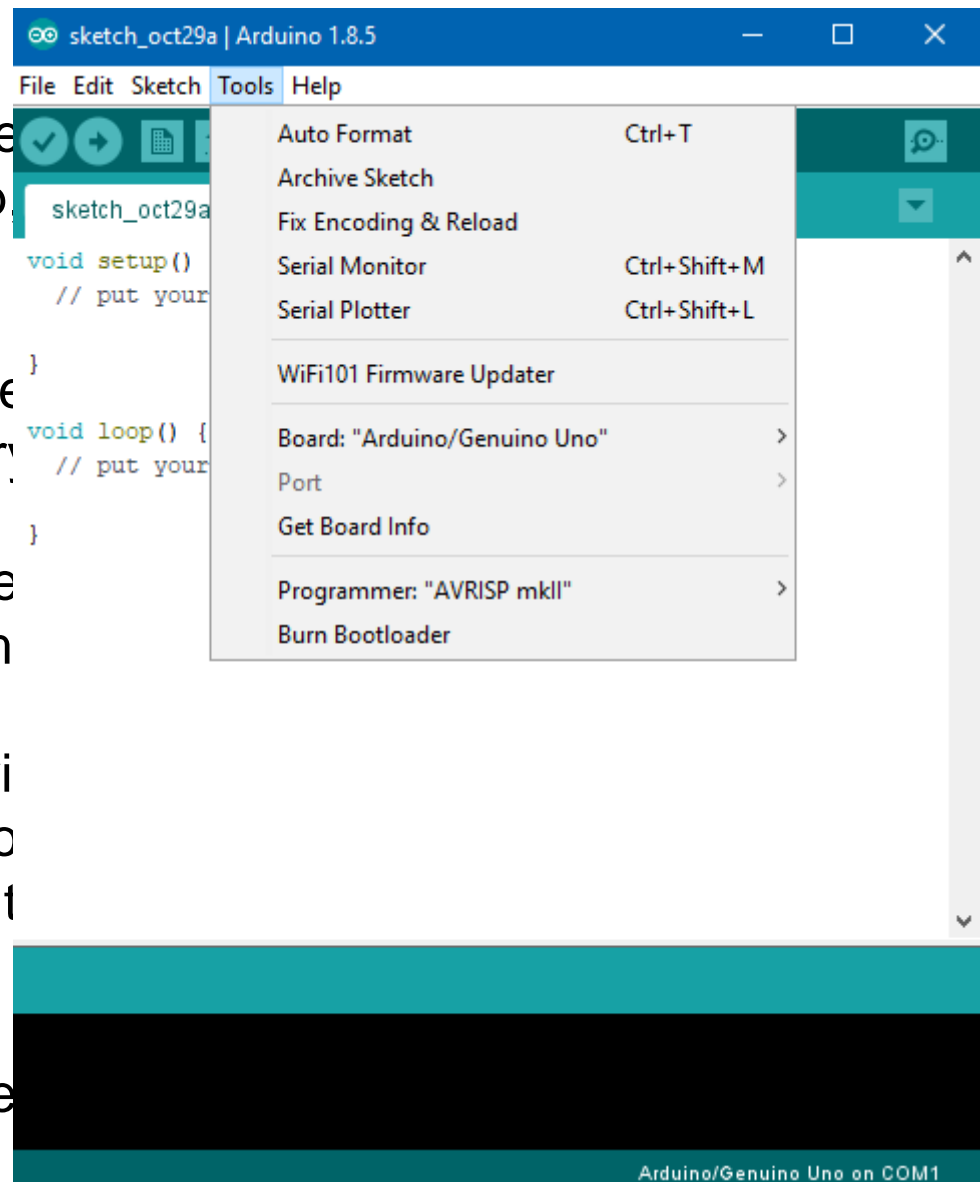
Fixes possible discrepancy and other operating system

- ***Serial Monitor***

Opens the serial monitor with any connected board or usually resets the board, if it is opening.

- ***Board***

Select the board that you're using [various boards](#).



# Tools

- ***Port***

This menu contains all the serial devices (real or virtual) on your machine. It should automatically refresh every time you open the top-level tools menu.

- ***Programmer***

For selecting a hardware programmer when programming a board or chip and not using the onboard USB-serial connection. Normally you won't need this, but if you're burning a bootloader to a new microcontroller, you will use this.

- ***Burn Bootloader***

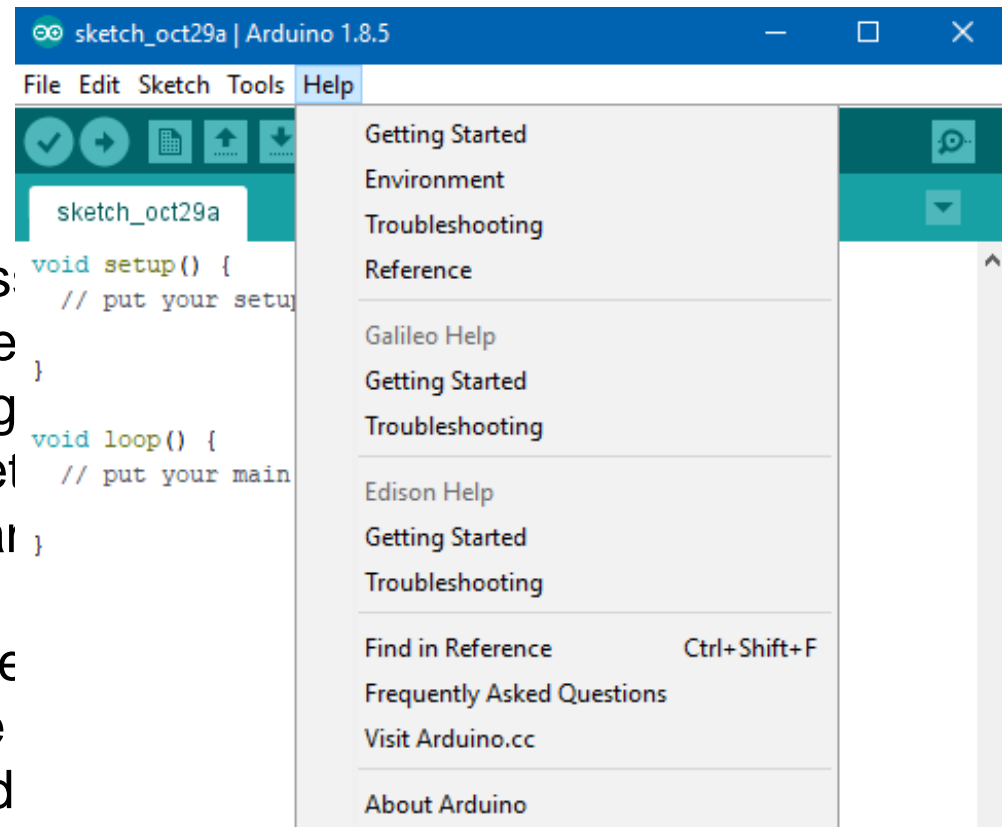
The items in this menu allow you to burn a bootloader onto the microcontroller on an Arduino board. This is not required for normal use of an Arduino or Genuino board but is useful if you purchase a new ATmega microcontroller (which normally come without a bootloader). Ensure that you've selected the correct board from the **Boards** menu before burning the bootloader on the target board. This command also set the right fuses.

# Help

Here you find easy access to the Arduino Software Reference, this guide is available locally, without an internet connection, as a copy of the online ones are available online.

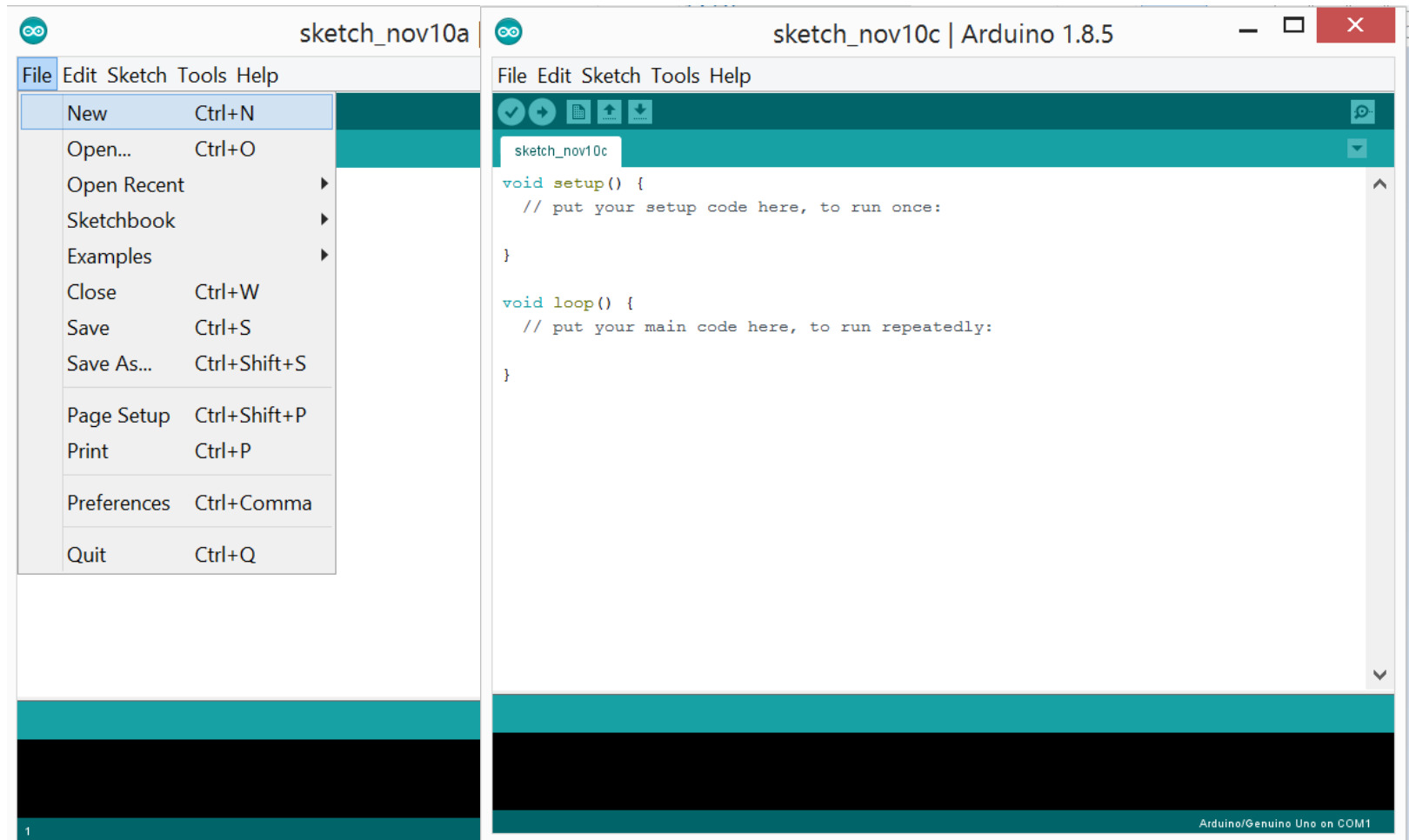
- ***Find in Reference***

This is the only interactive feature that allows you to select the relevant page, function or command and search for it.



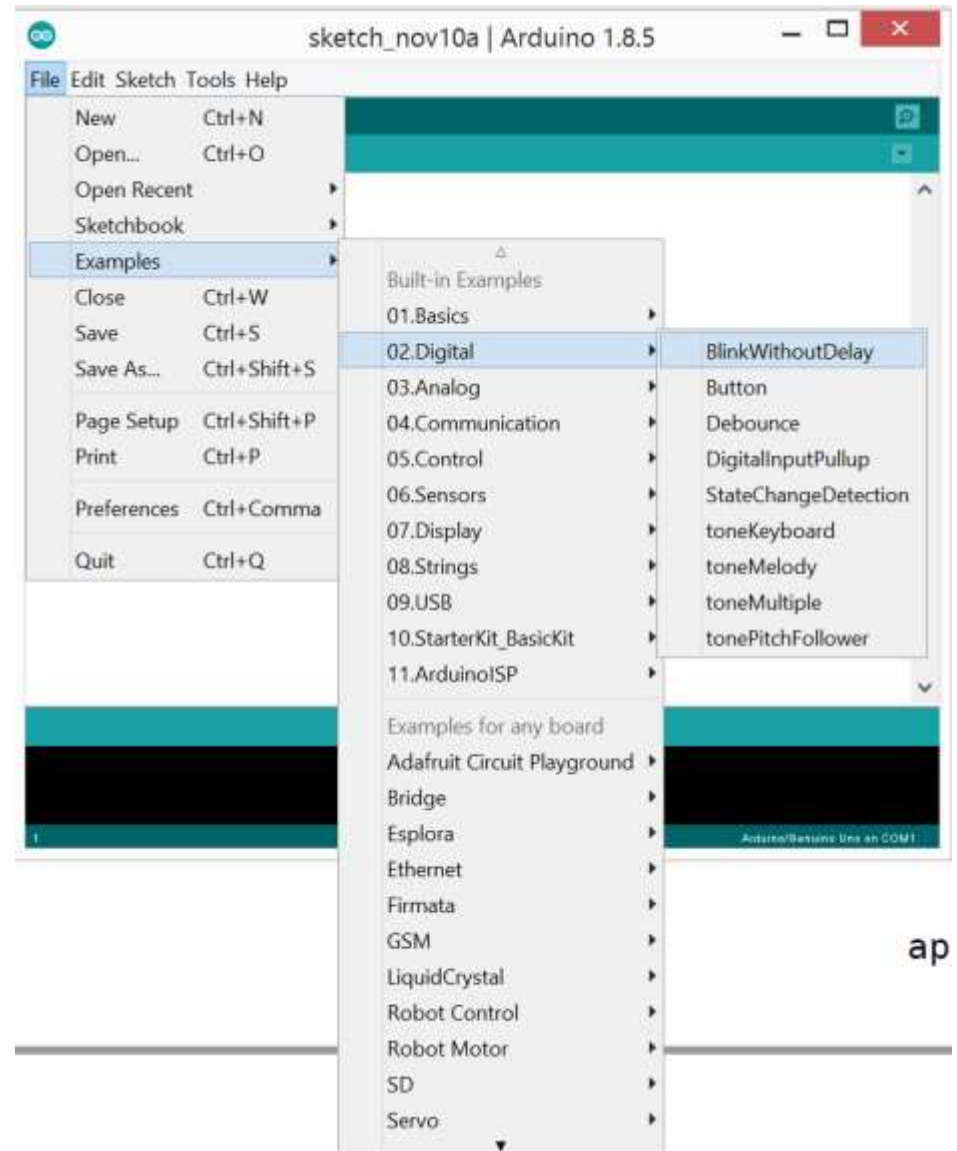
# First project

File -> New



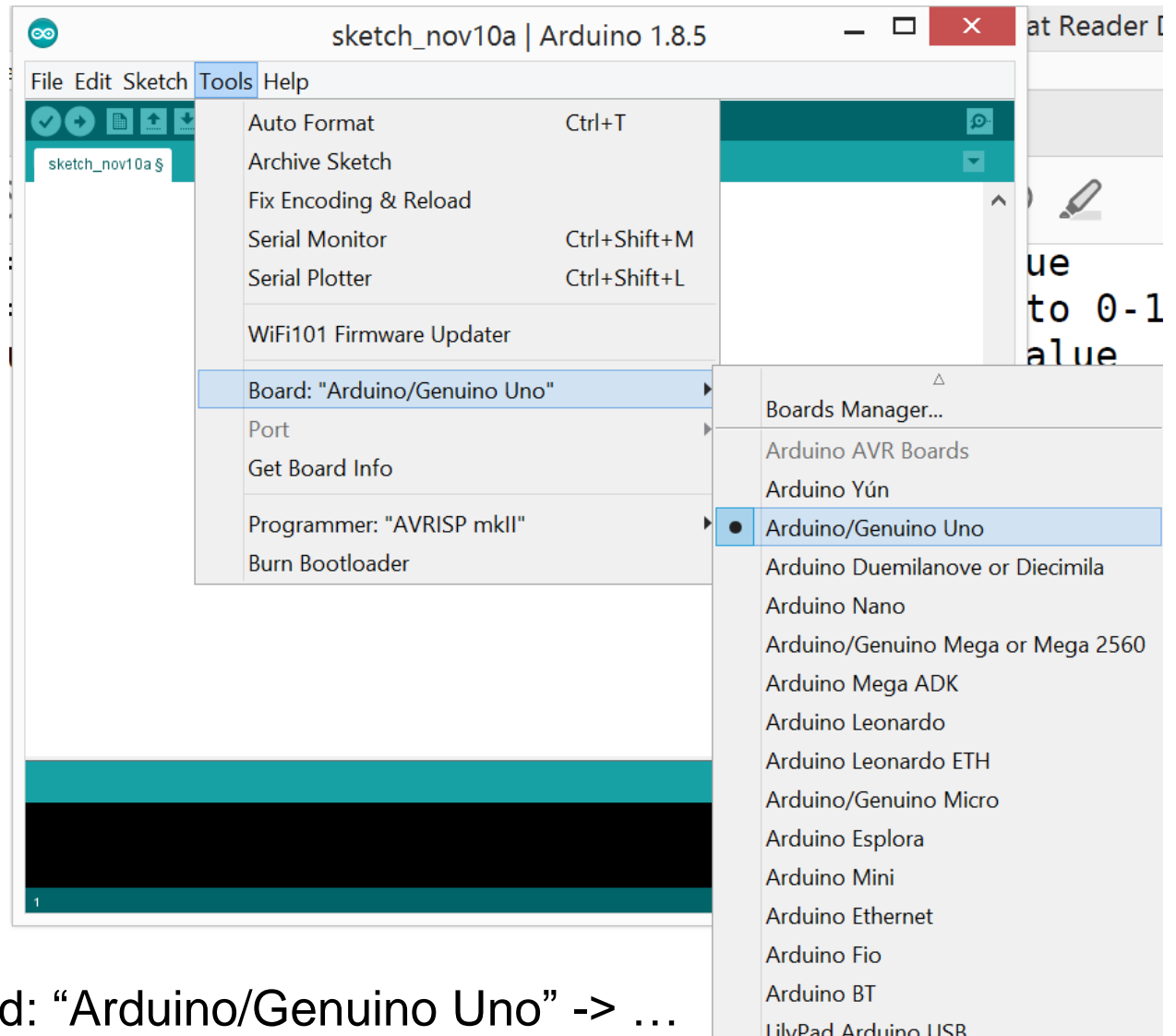
# First project

File -> Example -> ...



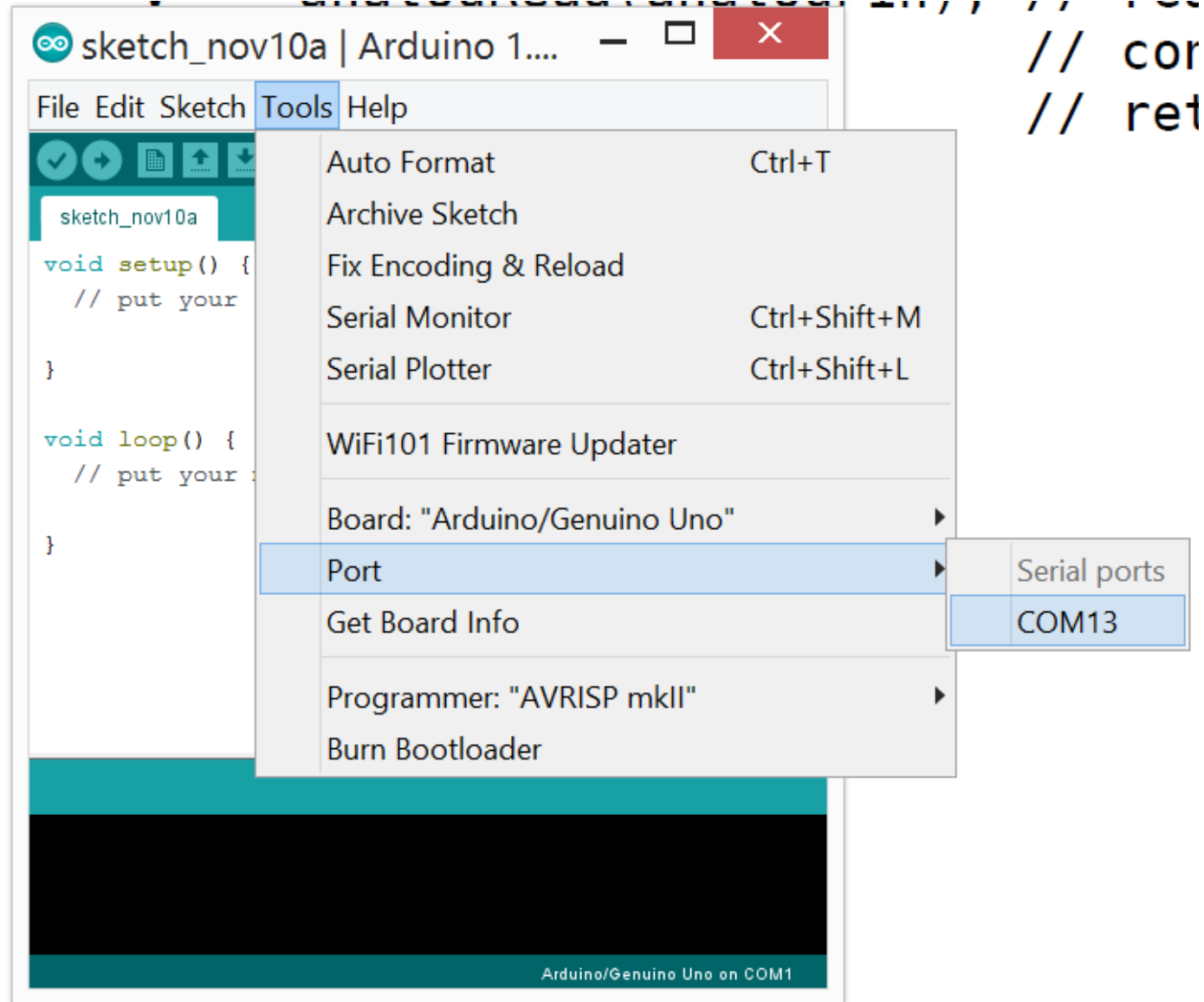


# Select Arduino board

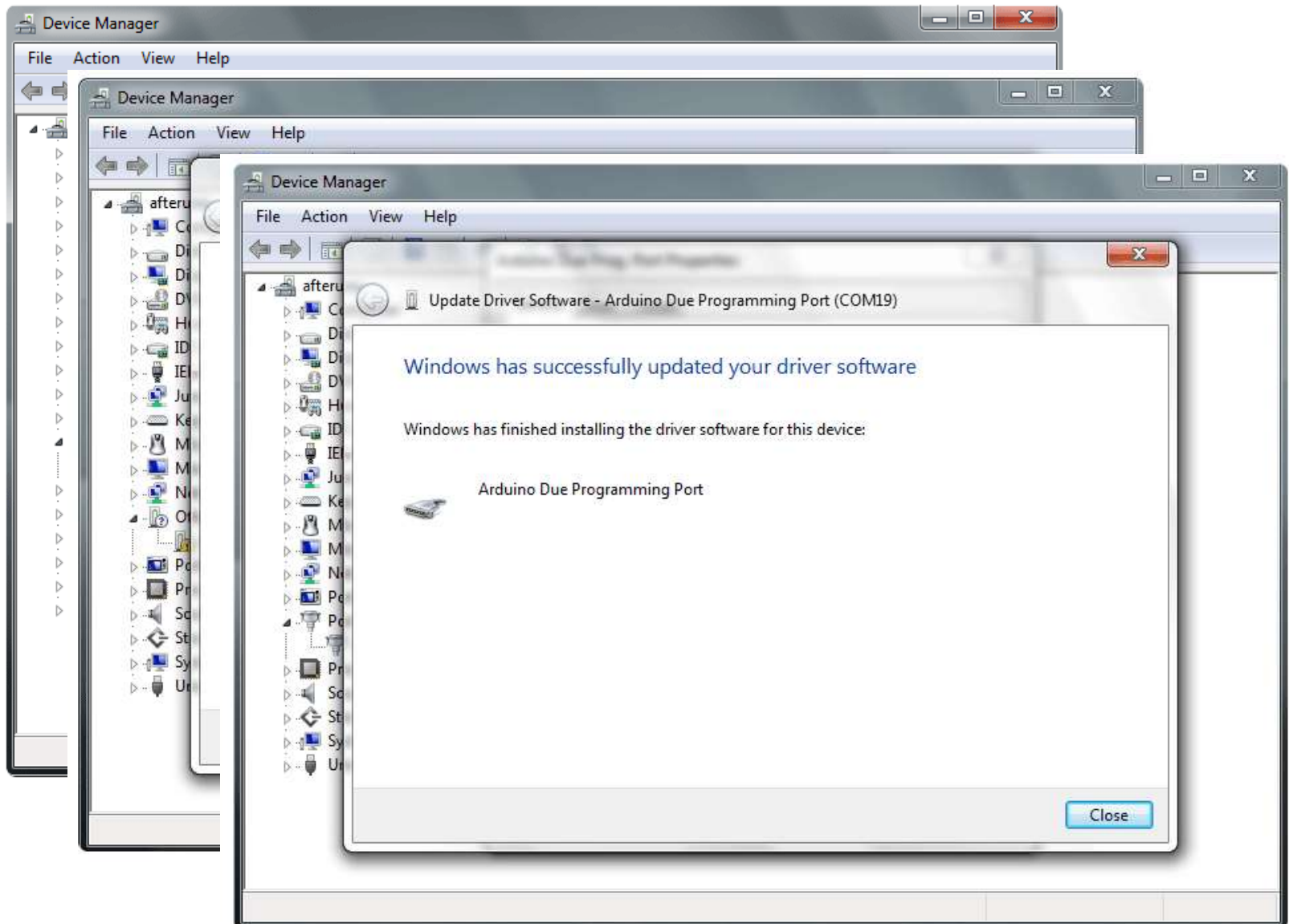


Tools -> Board: "Arduino/Genuino Uno" -> ...

# Select serial port

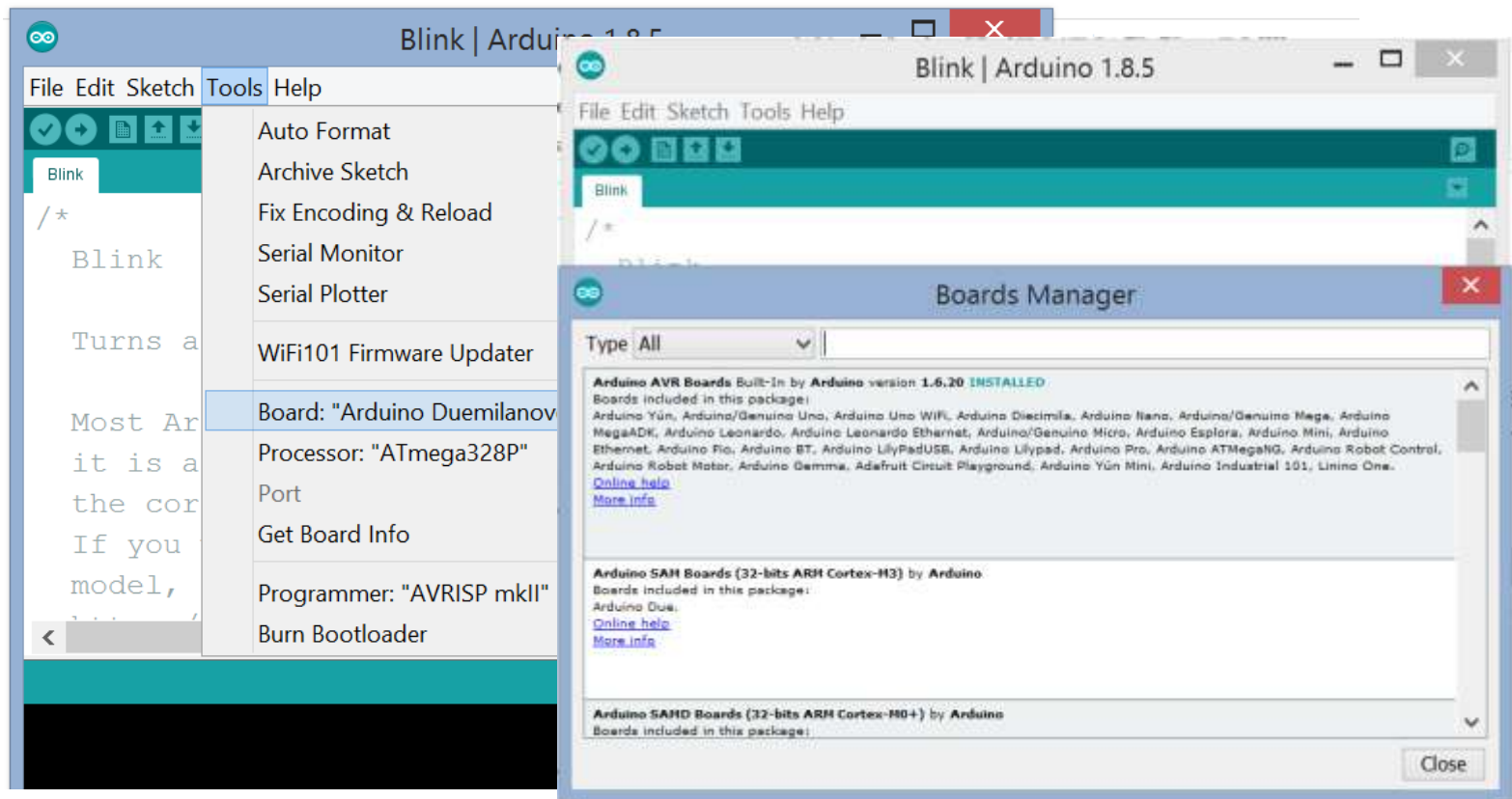


# Drivers Install (Win 7)



# Core install

- Some Arduino boards require an additional Core to be installed. Ex. For Arduino Due an Arduino board based on a 32-bit ARM core microcontroller
- you need to install the SAM Core using the Boards Manager



# Scketh toolbar



**Verify**



**Upload**



**New**



**Open**



**Save**



**Serial Monitor**



# Typical software code

```
void setup() {  
  // put your setup code here, to run once:  
  
}  
  
void loop() {  
  // put your main code here, to run repeatedly:  
  
}
```

Programs written using Arduino Software (IDE) are called sketches.

# Language reference

<https://www.arduino.cc/reference/en/#functions>

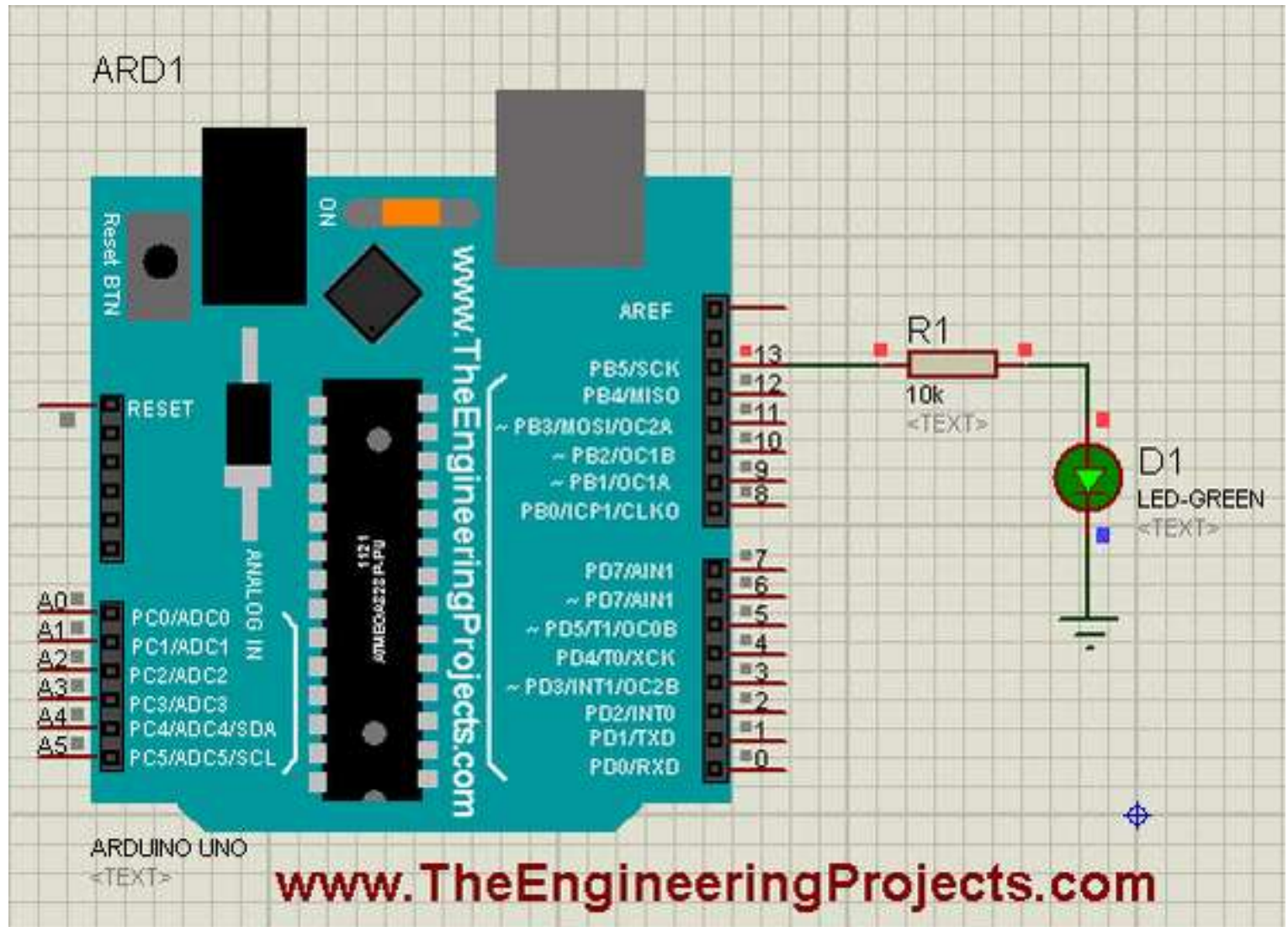
- **LANGUAGE**
- **FUNCTIONS**
- **VARIABLES**
- **STRUCTURE**

# IDE and SKETCH overview

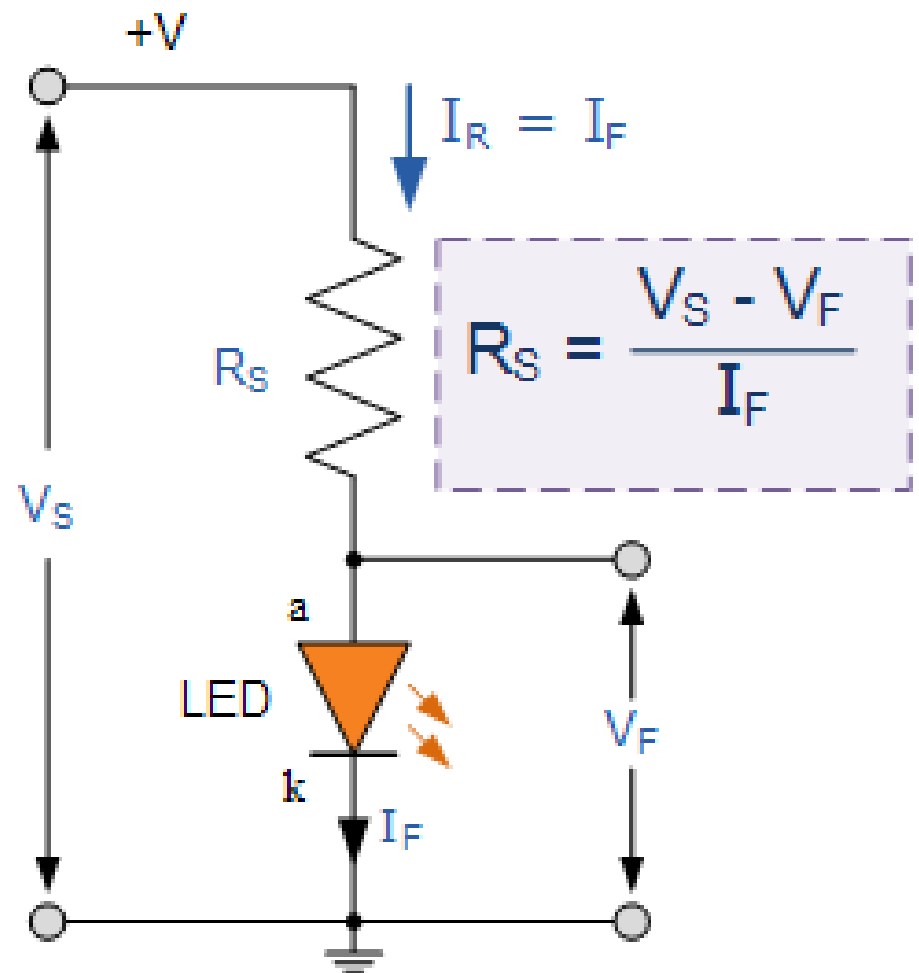
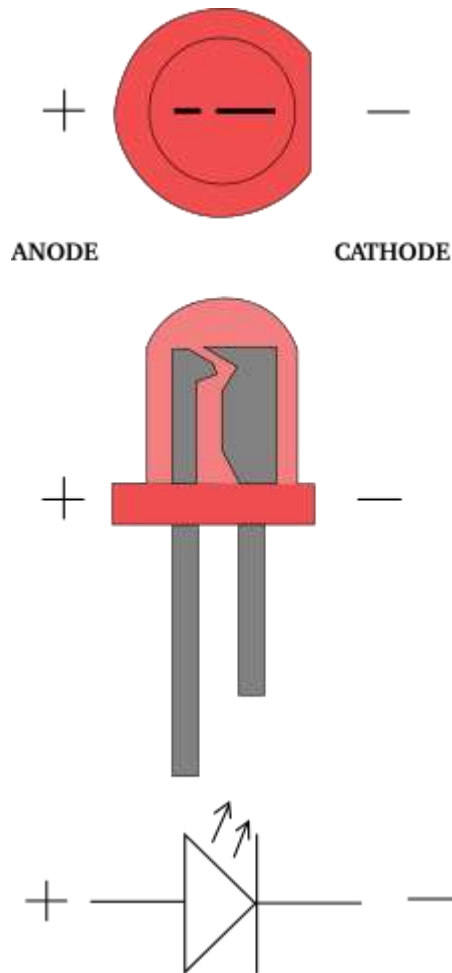
- ; semi-colons
- // single line comments
- /\* \*/ multi-line comments
- { } open and closing curly braces
- ( ) parenthesis
- void setup() – identify the opening and closing curly braces
- void loop() – identify the opening and closing curly braces
- some blue keywords like OUTPUT or INPUT

<https://programmingelectronics.com/tutorial-3-arduino-ide-and-sketch-overview/>

# Example: Led Blink



# Example: Led Blink





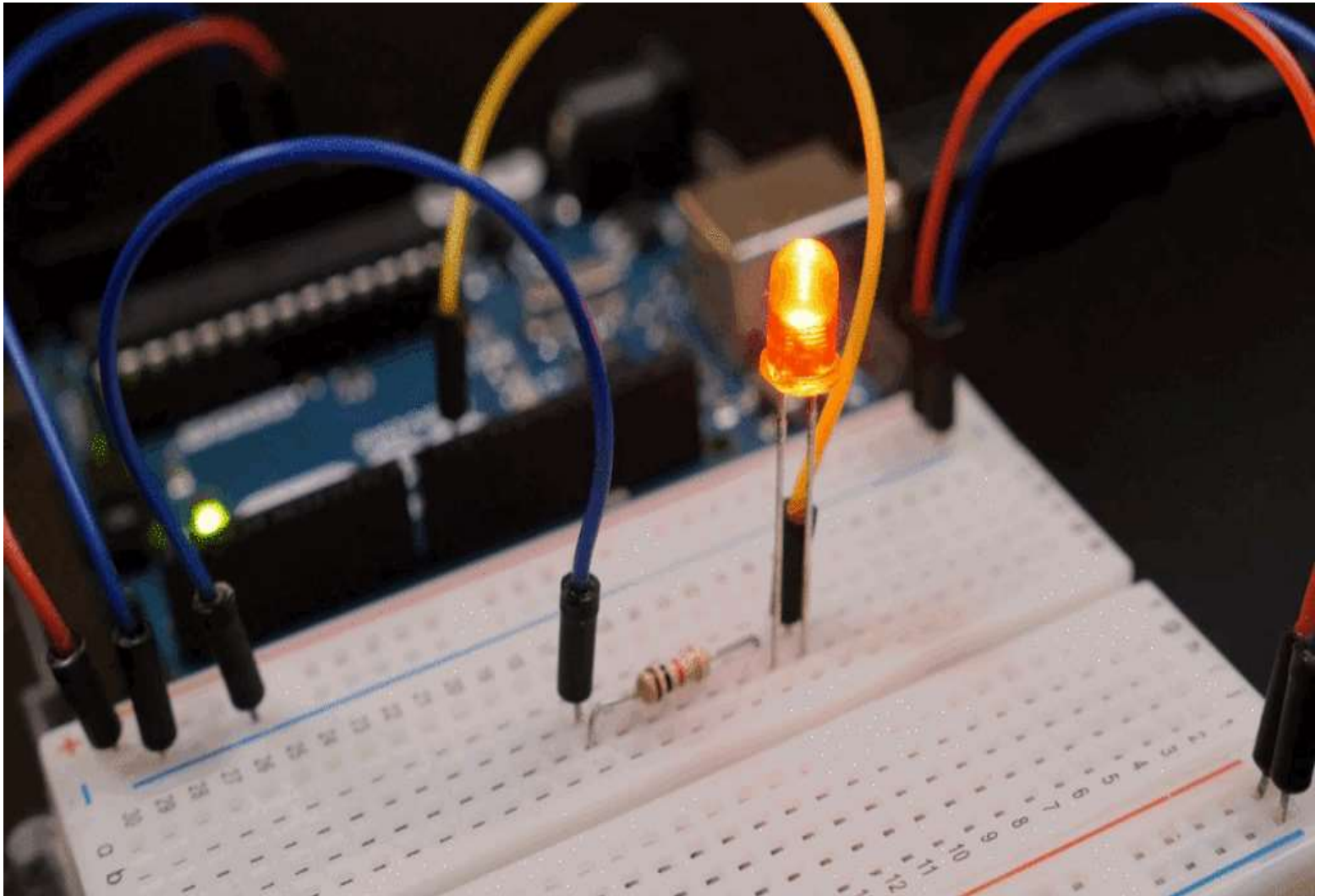
# Example: Led Blink

```
void setup()
{
  pinMode(13, OUTPUT);
}
void loop()
{
  digitalWrite(13, HIGH);
  delay(1000); //delay 1000 ms
  digitalWrite(13, LOW);
  delay(1000); //delay 1000 ms
}
```

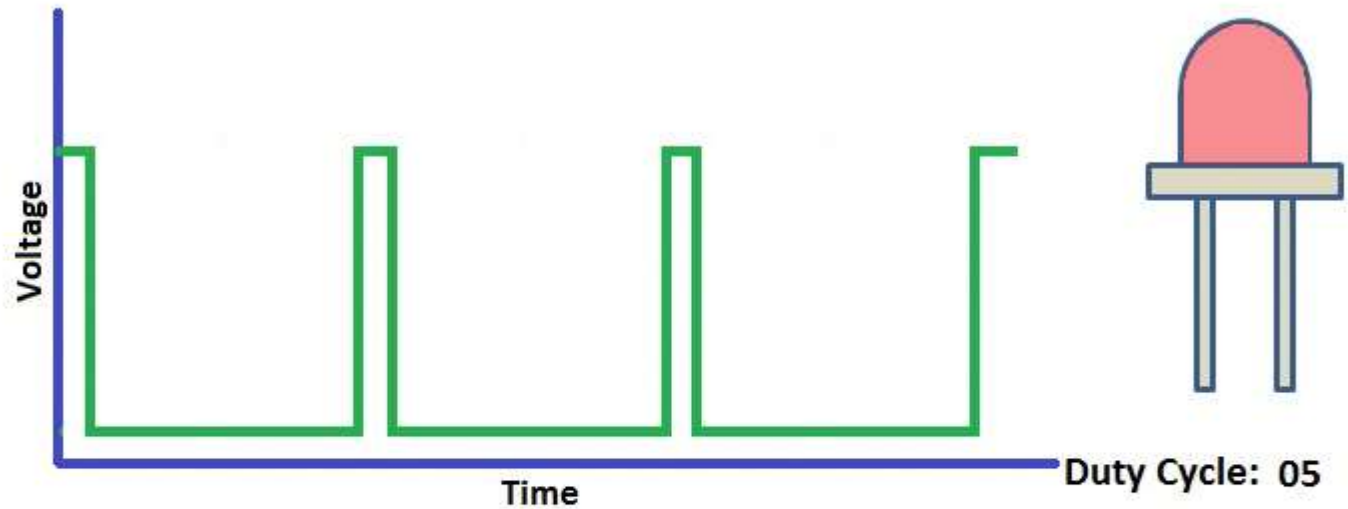
# Example: Built-in LED Blink

```
void setup()
{
    pinMode(LED_BUILTIN, OUTPUT);
}
void loop()
{
    digitalWrite(LED_BUILTIN, HIGH);
    delay(500);
    digitalWrite(LED_BUILTIN, LOW);
    delay(500);
}
```

# Example: variable intensity Led Brick



# Example: variable intensity Led Blink



**Frequency > 50Hz**

Only 6 pins can generate PWM signal (3, 5, 6, 9, 10 and 11)

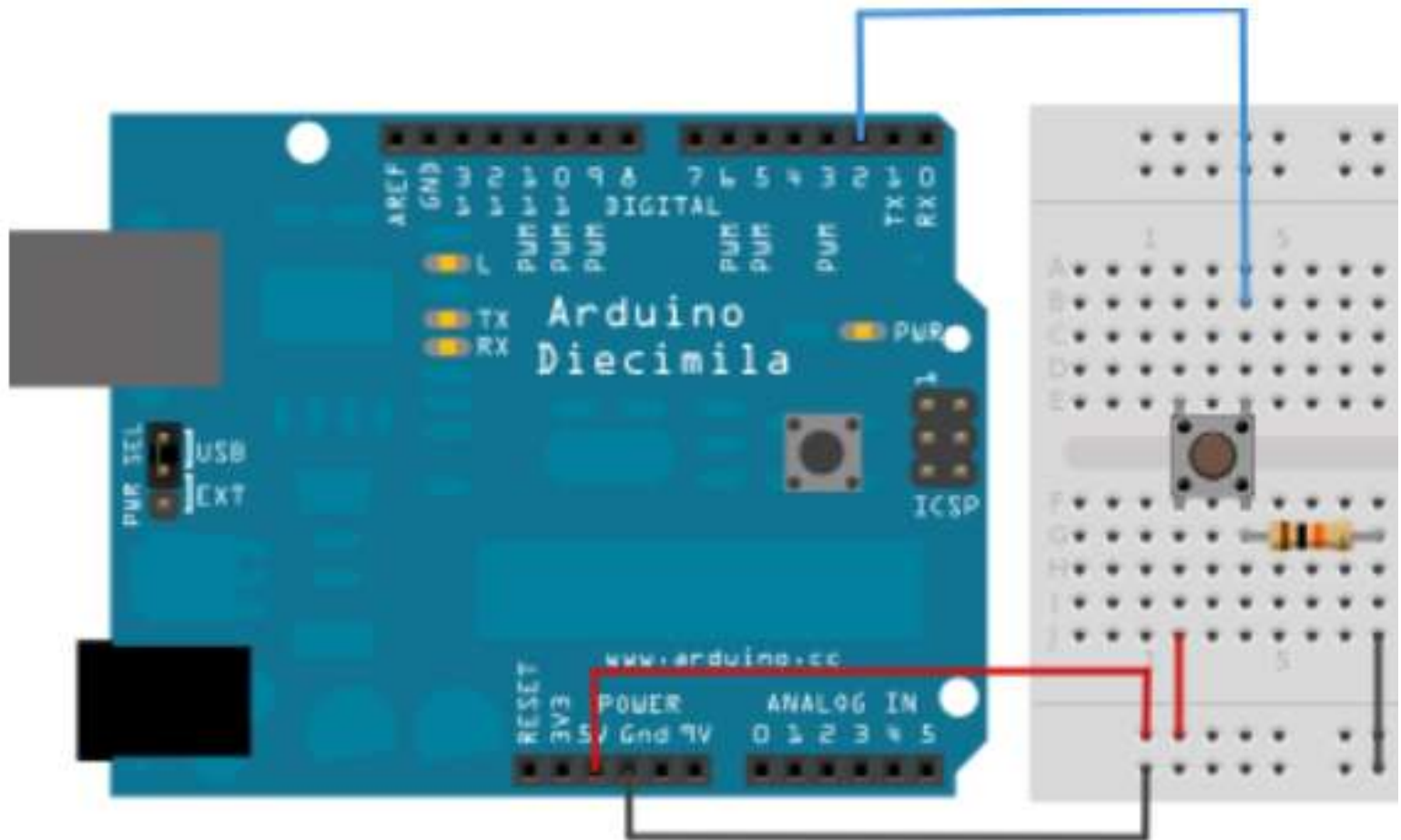
# Example: variable intensity LED Blink

- It is used pin 11
- Duty factor between 0 and 255

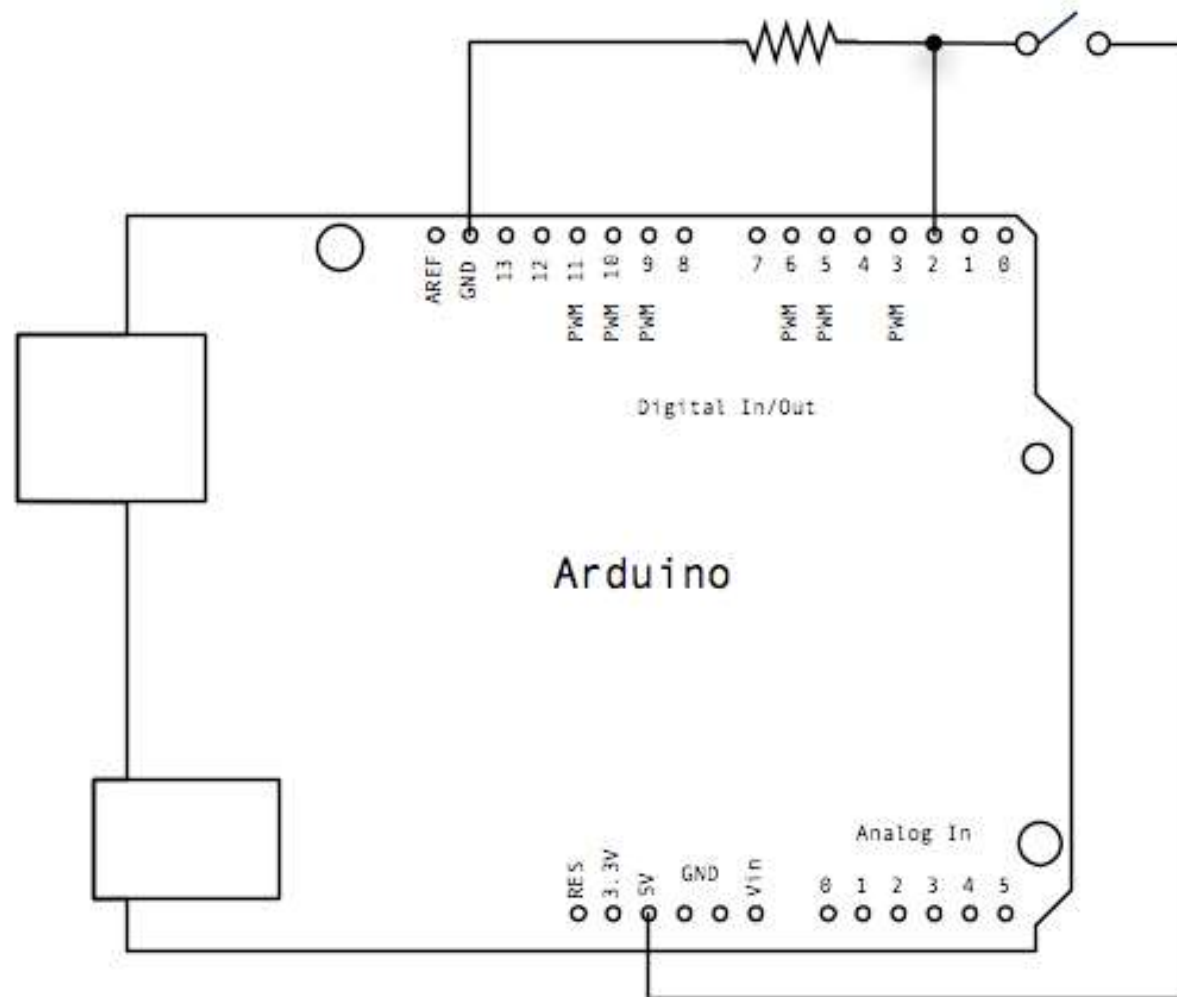
```
void setup() {  
    pinMode(11, OUTPUT);  
}  
void loop() {  
    for (int i = 0; i < 255; i++)  
    {  
        analogWrite(11, i);  
        delay(50);  
    }  
    for (int i = 255; i > 0; i--) {  
        analogWrite(11, i);  
        delay(50);  
    }  
}
```



# Example: Button



# Example: Button



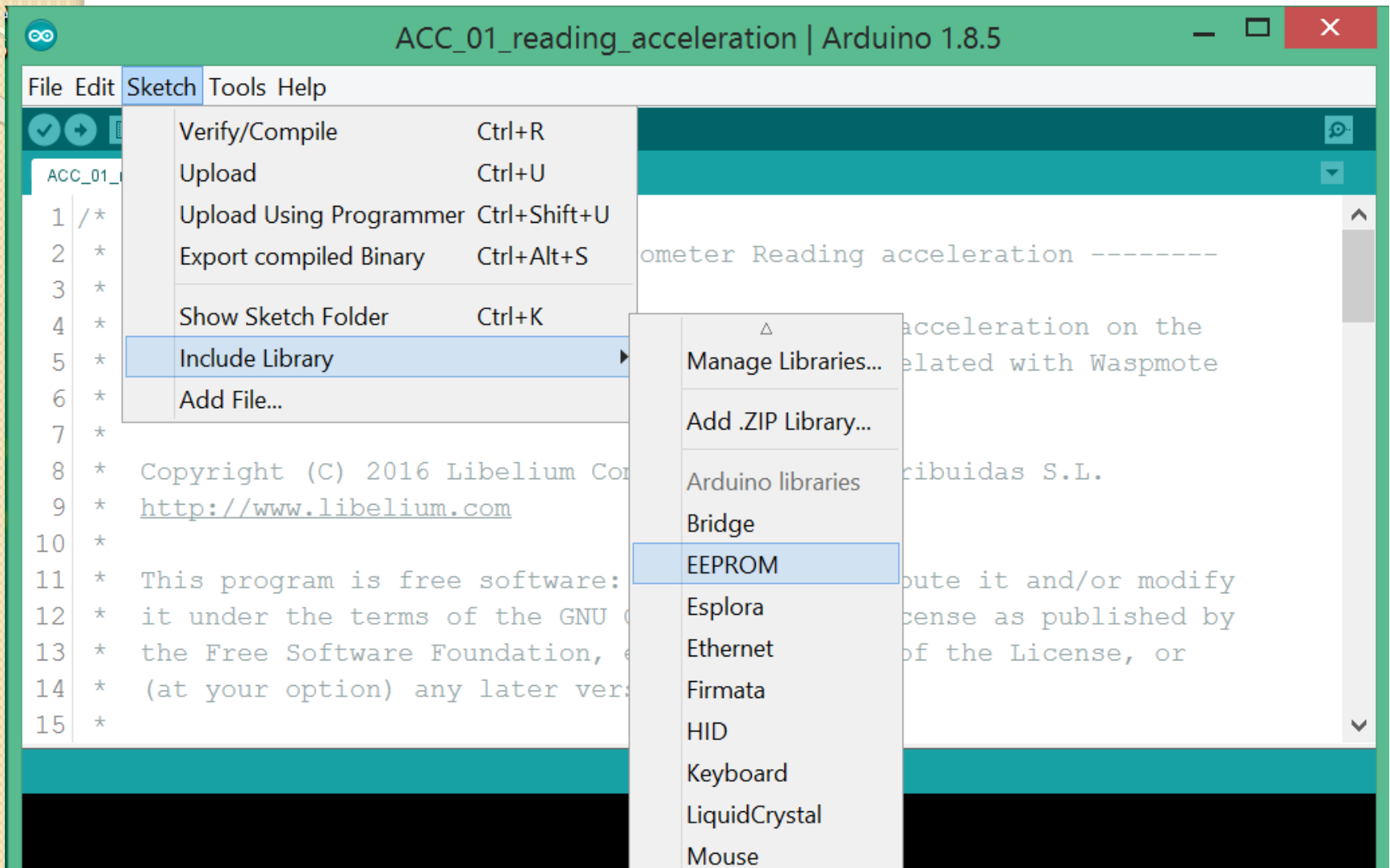
# Example: Button

```
const int buttonPin = 2;    // the number of the pushbutton pin
const int ledPin = 13;     // the number of the LED pin
int buttonState = 0;       // variable for reading the pushbutton
status

void setup() {
  pinMode(ledPin, OUTPUT);
  pinMode(buttonPin, INPUT);
}

void loop() {
  buttonState = digitalRead(buttonPin);
  if (buttonState == HIGH) {
    digitalWrite(ledPin, HIGH);
  } else {
    digitalWrite(ledPin, LOW);
  }
}
```

# Library Arduino



# Library Arduino

**EEPROM** - reading and writing to "permanent" storage

**Ethernet / Ethernet 2** - for connecting to the internet using the Arduino Ethernet Shield, Arduino Ethernet Shield 2 and Arduino Leonardo ETH

**Firmata** - for communicating with applications on the computer using a standard serial protocol.

**GSM** - for connecting to a GSM/GPRS network with the GSM shield.

**LiquidCrystal** - for controlling liquid crystal displays (LCDs)

**SD** - for reading and writing SD cards

**Servo** - for controlling servo motors

**SPI** - for communicating with devices using the Serial Peripheral Interface (SPI) Bus

**SoftwareSerial** - for serial communication on any digital pins. Version 1.0 and later of Arduino incorporate Mikal Hart's NewSoftSerial library as SoftwareSerial.

**Stepper** - for controlling stepper motors

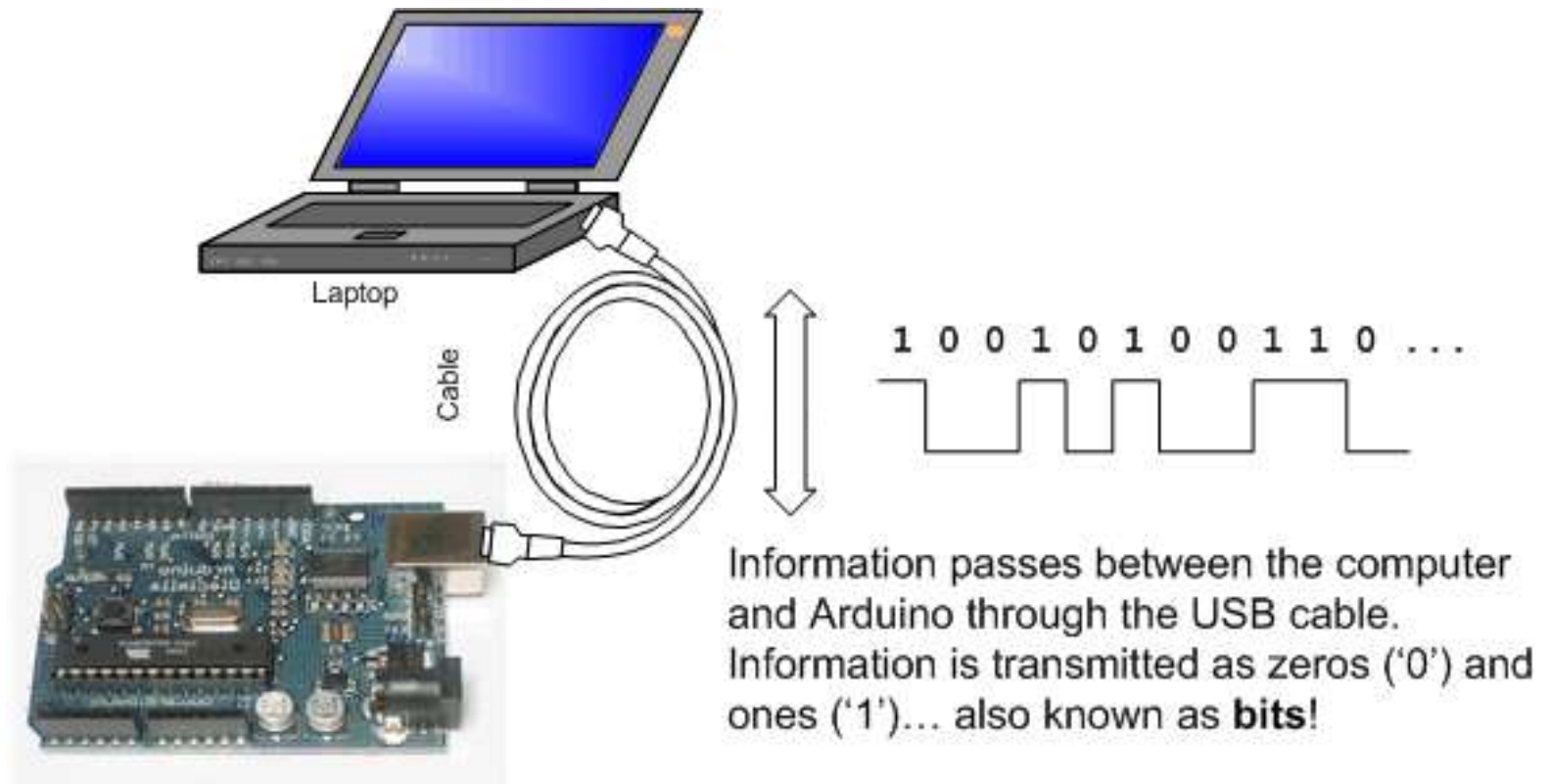
**TFT** - for drawing text, images, and shapes on the Arduino TFT screen

**WiFi** - for connecting to the internet using the Arduino WiFi shield

**Wire** - Two Wire Interface (TWI/I2C) for sending and receiving data over a net of devices or sensors.

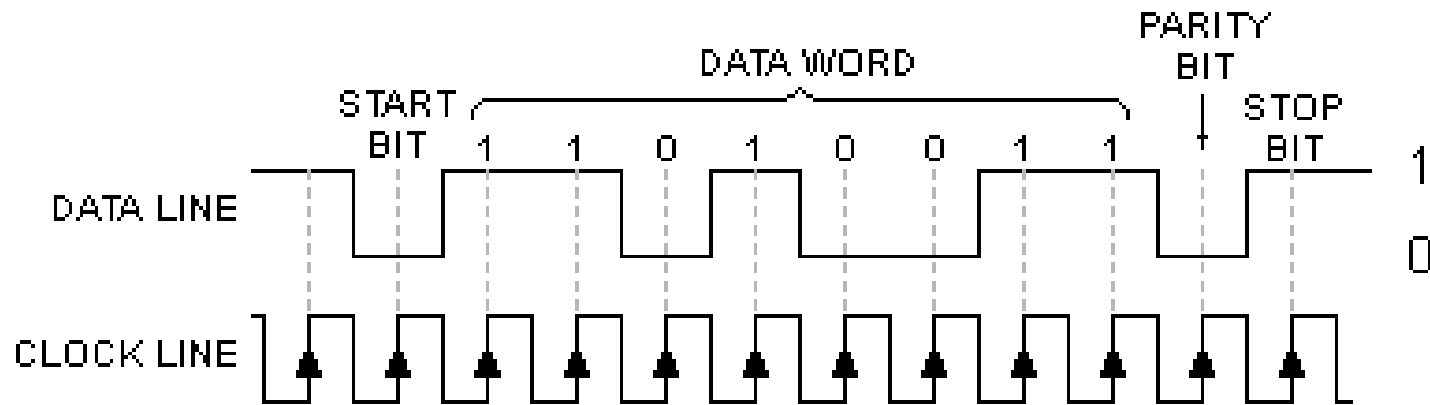
<https://www.arduino.cc/en/Reference/Libraries>

# Example: Serial transmission





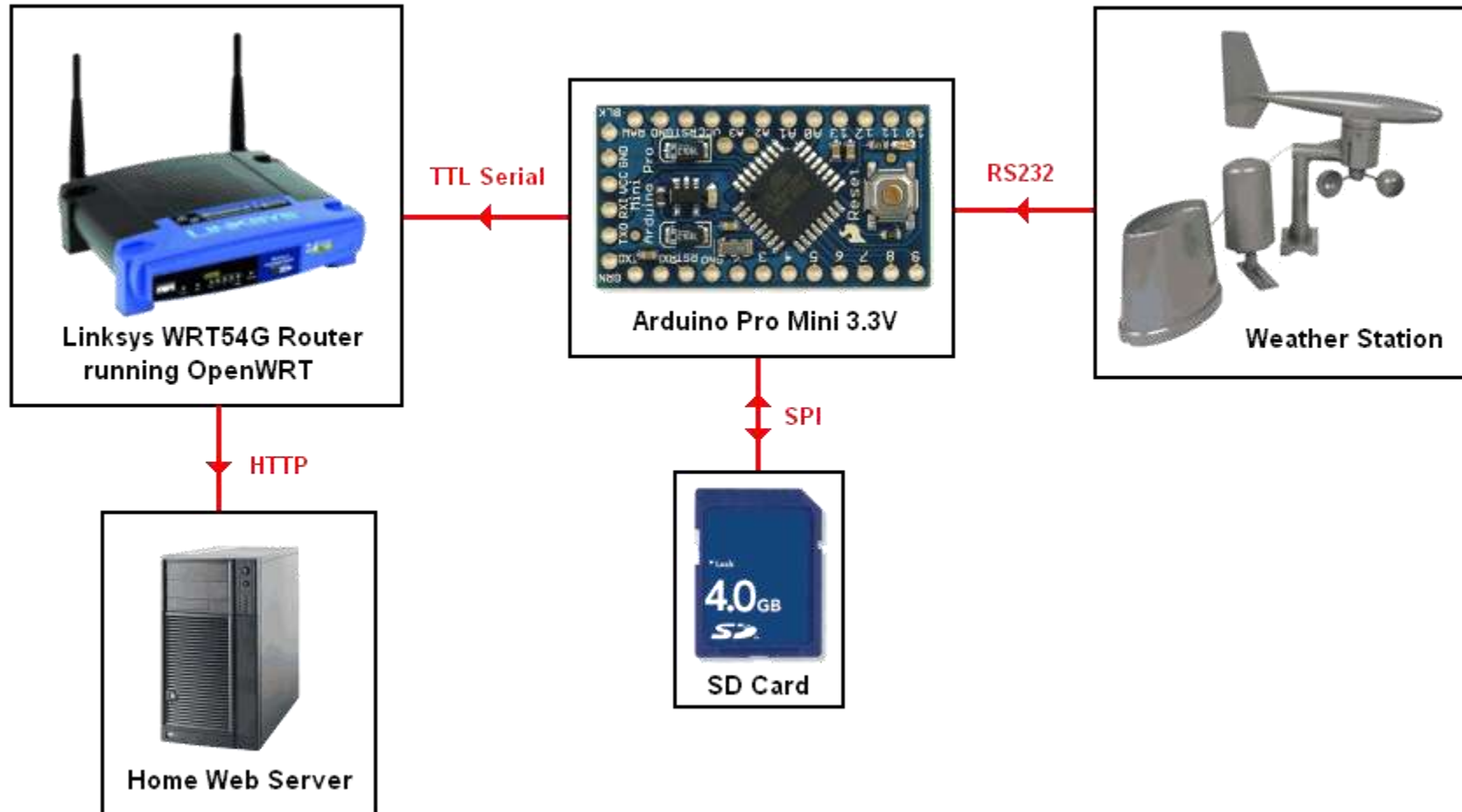
# Example: Serial transmission



“standard” baud are 1200, 2400, 4800, 19200, 38400, 57600, and 115200

Eg. 9600 bps

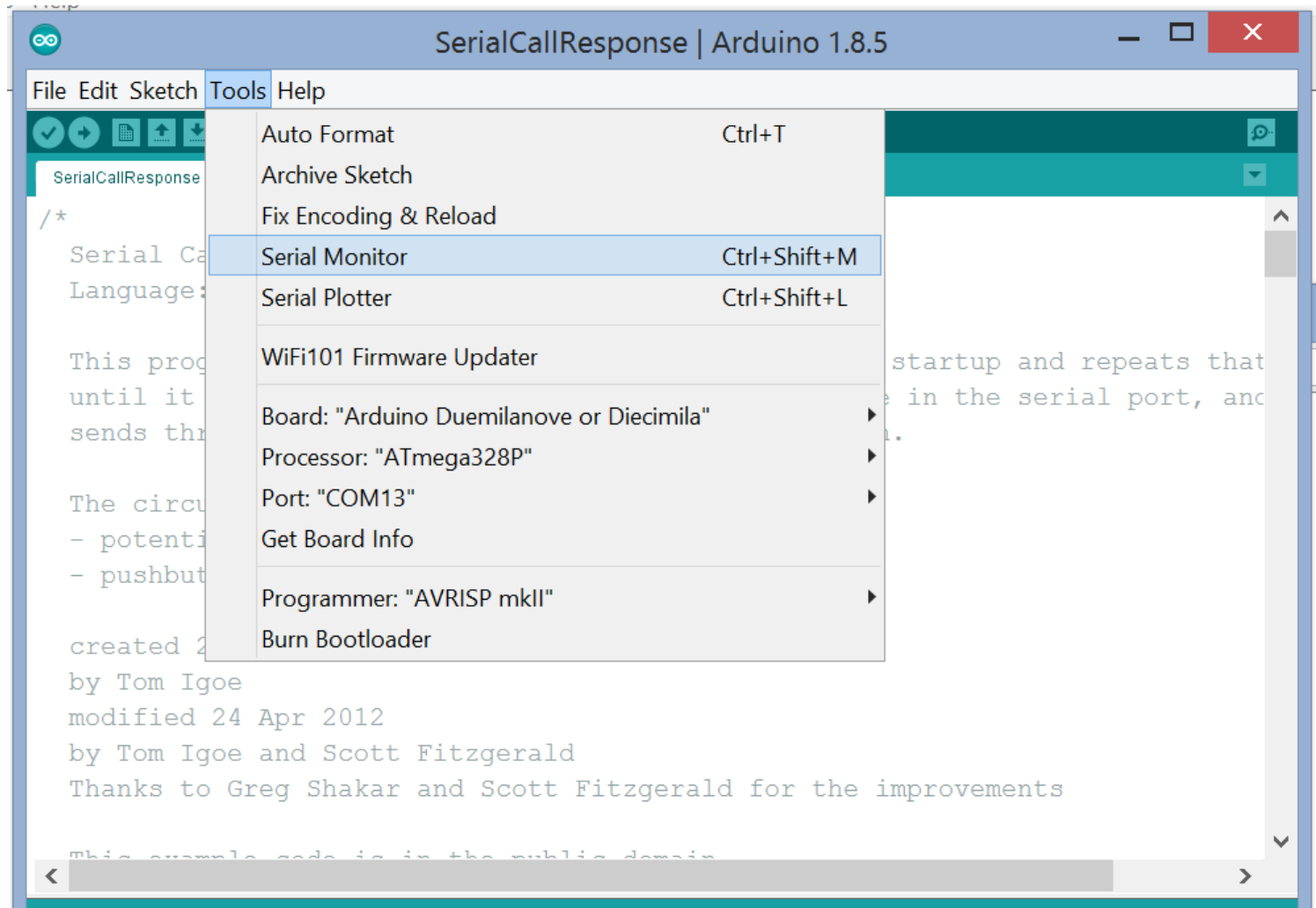
# Serial transmission applications



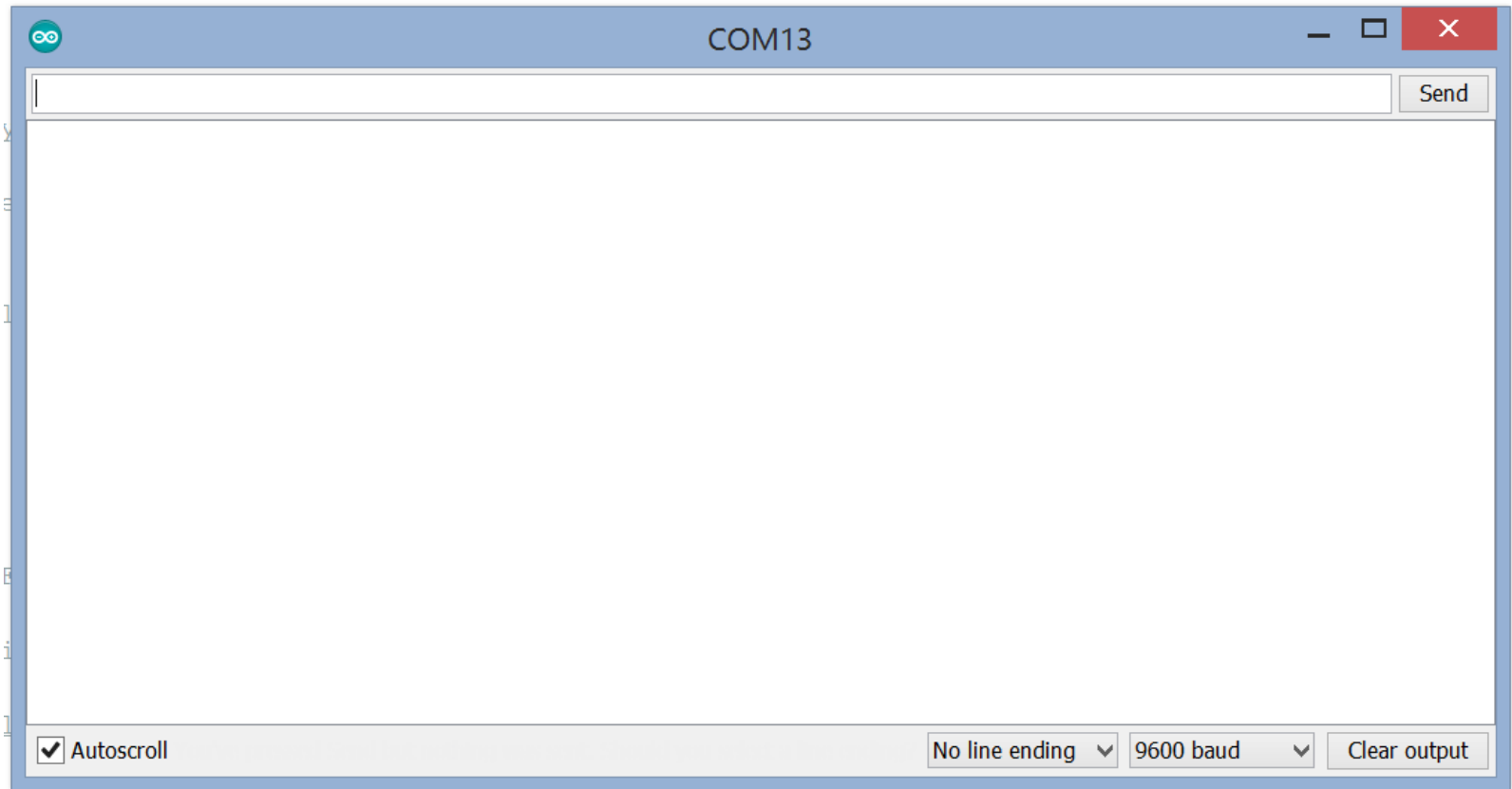
# Serial communication

```
void setup() {  
    Serial.begin(9600);  
    Serial.println("Hello!");  
}  
void loop()  
{  
  
}
```

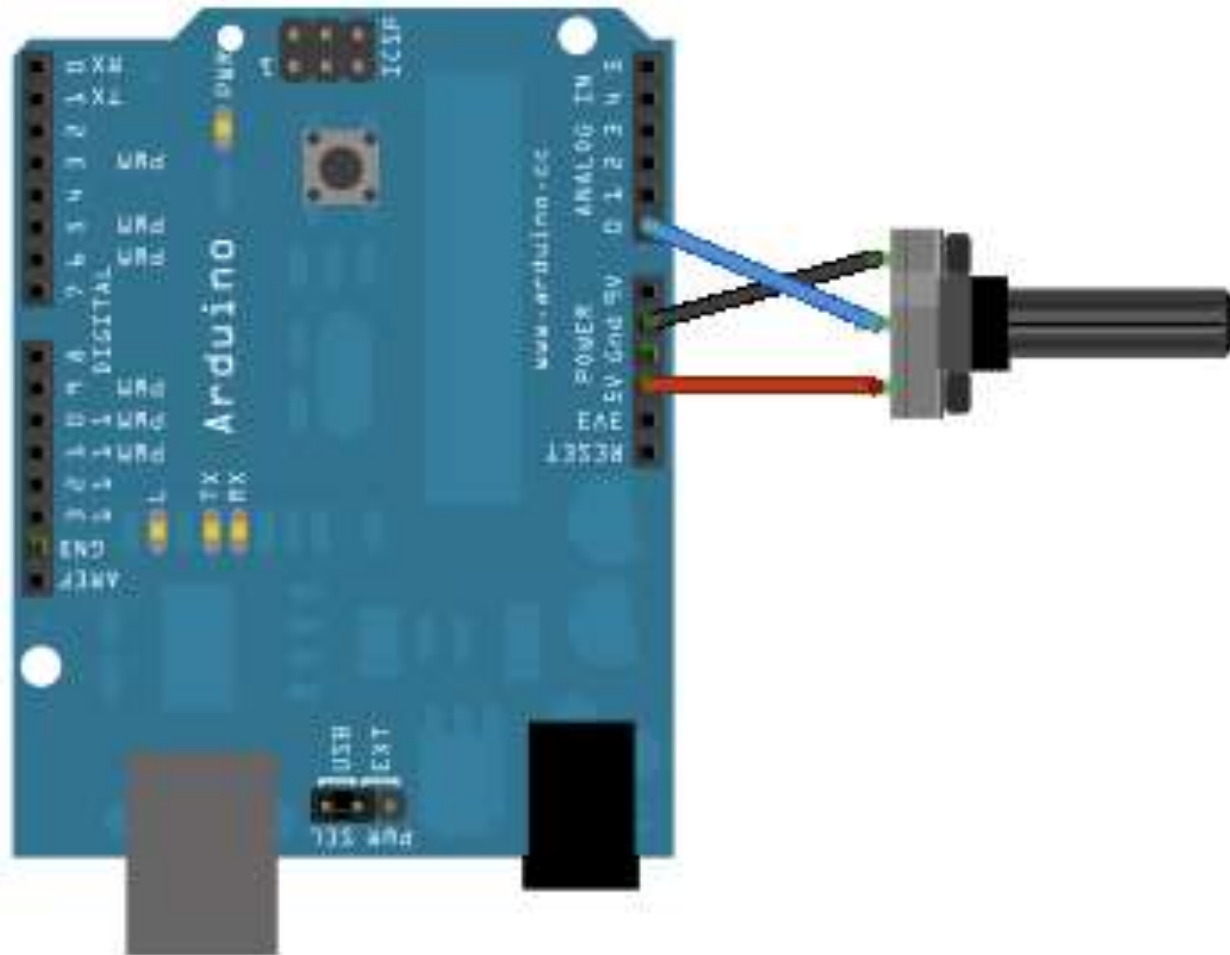
# Serial communication



# Serial communication

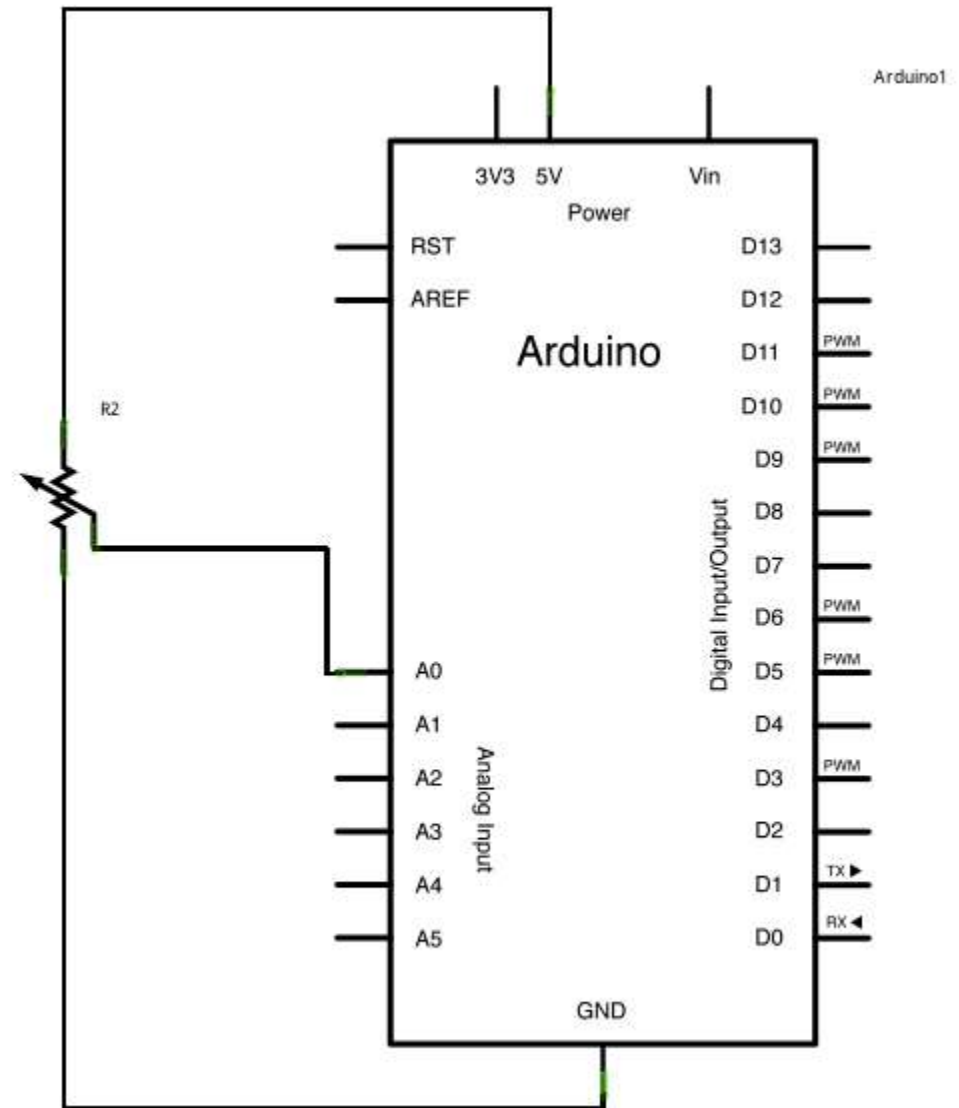


# Example: Read analogue value





# Example: Read analogue value



# Example: Read analogue value

```
void setup() {  
    // initialize serial communication  
    Serial.begin(9600);  
}  
  
void loop() {  
    // read the input on analog pin 0:  
    int sensorValue = analogRead(A0);  
    // print out the value you read:  
    Serial.println(sensorValue);  
    delay(100); //delay for stability  
}
```

# Review

- Types of arduino board
- IDE programming tools
- Basic examples

# Questions?



SonnetteCenterblog